

# Dynamics on Networks and Lattices

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*A dissertation submitted for the partial fulfilment  
of BS-MS dual degree in Science*



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## Certificate of Examination

This is to certify that the dissertation titled **Dynamics on Networks and Lattices** submitted by **Vidit Agrawal** (Reg. No. MS09134) for the partial fulfillment of BS-MS dual degree programme of the Institute, has been examined by the thesis committee duly appointed by the Institute. The committee finds the work done by the candidate satisfactory and recommends that the report be accepted.

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## Declaration

The work presented in this dissertation has been carried out by me under the guidance of Prof. Sudeshna Sinha at the Indian Institute of Science Education and Research Mohali.

This work has not been submitted in part or in full for a degree, a diploma, or a fellowship to any other university or institute. Whenever contributions of others are involved, every effort is made to indicate this clearly, with due acknowledgement of collaborative research and discussions. This thesis is a bonafide record of original work done by me and all sources listed within have been detailed in the bibliography.

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In my capacity as the supervisor of the candidates project work, I certify that the above statements by the candidate are true to the best of my knowledge.

Prof. Sudeshna Sinha  
(Supervisor)



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I would like to thank Prof. Sudeshna Sinha for her guidance and support in the successful completion of my final year thesis project.

Vidit Agrawal

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# Notation

## Chapter-1

$\epsilon$	Coupling Parameter
$p_s$	Probability of random links
$p_t$	Probability of link change
$\eta$	site of 1 <sup>st</sup> neighbour (randomly chosen with probability $p_s$ and regularly chosen with $(1 - p_s)$ )
$\xi$	site of 2 <sup>nd</sup> neighbour (randomly chosen with probability $p_s$ and regularly chosen with $(1 - p_s)$ )
$Z(n)$	Synchronization error function
$T_{sync}$	Time to reach synchronization
$L_{intermittant}$	Time duration of intermittant behavior

## Chapter-2

$\tau_0$	Total period of disease cycle
$\tau_I$	Period for which individual is infected
$\tau_R$	Period for which individual is refractory/immune
$S_0$	Initial fraction of Susceptible individuals in the population
$R_0$	Initial fraction of Refractory individuals in the population
$I_t$	Fraction of Infected individuals in the population at time 't'
$\eta$	Initial fraction of refractory population having randomly different phases
$\chi$	Range from which initial phases of refractory individuals is taken

## Abstract

**Chapter-1** Connection topology is the key to controlling the spatio-temporal dynamics of coupled maps, and varying the fraction of random links can tune the system from spatio-temporal chaos to synchronized stable fixed points. Here we consider a network of chaotic maps, where the sites connect to nearest neighbours with probability  $(1 - p_s)$ , and to random non-local sites with probability  $p_s$ . Further we consider that the underlying links in the system can switch with probability  $p_t$ , keeping the average fraction of random links the same. This implies that when  $p_t$  is unity, the links in the network change at each iteration, with the new links being random with probability  $p$ . We study two kinds of variation of the links. We consider the scenario where the links change independently at the local level, namely, the coupling connections of every node is switched with probability  $p_t$ . Our central result is that the probabilistic switching of links, at the local or global level, yields a sharply increasing range of synchronized fixed point, as one goes from a completely static network to completely dynamic one. Further, for small  $p_t$ , we observe that different realizations of the connectivity matrix, with the same fraction of random links, synchronizes at different values of coupling strength, and so there is a spread in the values of the critical coupling strength necessary for synchronization. However, as we go towards the completely dynamic limit ( $p_t = 1$ ) there is rapid convergence to a specific critical coupling strength, indicating that dynamic rewiring acts like a self-averaging mechanism, as the network evolves under many different connection matrices drawn from an ensemble of matrices with the same  $p$ , over time. The enhanced spatio-temporal regularity obtained under dynamic links is also verified through linear stability analysis about the synchronization manifold. Lastly, for low probabilities of link change, we find that the system shows intermittency, and as the links switch more frequently, this intermittency gives way to perfect synchronization.

**Chapter-2** We investigate the emergent infection spreading patterns in a population on 2-Dimensional lattice based on a cellular automata model of the SIRS disease cycle. We observed that in a population consisting of randomly distributed refractory and susceptible individuals, an infection seed can lead to persistent infection in the population. Further, our results suggest that the size of the infected sub-population depends on the dynamical characteristics of the disease cycle, and on the heterogeneity of the population in which the disease spreads.



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# Chapter 1

## Regularizing influence of Dynamical Links

### 1.1 Introduction

Networks of coupled dynamical systems capture the essential spatiotemporal features of large interactive systems with complex dynamics at the local scale [13]. Most studies so far have focussed on static networks. However, in many realistic scenarios the links between the constituent sub-systems are likely to change over time. In fact a wide range of extended systems of biological, technological and physical significance are better described by a dynamically changing web of connections. Motivated by this, we will study the spatiotemporal dynamics of networks of coupled systems where the links change with a certain prescribed probability.

### 1.2 Model

We consider a one dimensional ring of coupled strongly chaotic logistic maps. The sites are denoted by  $i = 1, 2, 3, \dots, N$  where  $N$  denotes the linear size of the lattice. The evolution of this lattice, in discrete time  $n$  is given by

$$x_{n+1}(i) = (1 - \epsilon)f[x_n(i)] + \frac{\epsilon}{2}\{x_n(\xi) + x_n(\eta)\} \quad (1.1)$$

where,

$$f(x) = 4x(1 - x) \quad (1.2)$$

and  $\epsilon$  is the coupling strength. We also define a parameter  $p_s$  which represents the probability of links being random. Here,  $\xi = i + 1$  with probability  $1 - p_s$  and is a randomly chosen integer  $\xi$  ( $1 \leq \xi \leq N$ ) with probability  $p_s$ . Similarly,  $\eta = i - 1$  with probability  $1 - p_s$



and is a randomly site with probability  $p_s$ . The  $p_s = 0$  case corresponds to regular nearest neighbour coupling and  $p_s = 1$  corresponds to completely random connections.

Now we consider a situation wher the connections in the network can vary in time. If the switching of links occurs at every dynamical time step, then it is a completely dynamic networks, aqnd if  $\xi$  and  $\eta$  do not change in time then it is a completely static network. Our focus here is to study the transition between these two limits. We do this through a parameter  $p_t$  which gives the probability with which a link in the network can change. If  $p_t = 0$  then we have the case of quenched links ( $\xi$  and  $\eta$  fixed in time) and if  $p_t = 1$  then all links switch at every time step.

So the link switching criterion is local, and the links of every node(site), at every instant of time, can change independently with probability  $p_t$ . It is evident then, that if a node swtiches links at a certain point in time, the other nodes may or may not switch their connections. The frequency of changing connections, on an average, is determined by the probability  $p_t$ . This is in contrast with the network changing all the links globally with a certain probability, i.e. the scenario where the entire connectivity matrix of the network changes at certain points in time.

In this work, we investigate the asymptotic dynamics of this network, evolving from random initial conditions. Specifically, we examine the spatiotemporal implications of varying the coupling strength  $\epsilon$ , and the link switching probabily  $p_t$ .

### 1.3 Analysis

Through extensive numerical simulations of this dynamical network we obtain bifurcation diagrams with respect to couplinbg strength  $\epsilon$ . From these bifurcation diagrams we find the critical coupling strength  $\epsilon_c$  such that one obtains spatio-temporal synchronization, namely a spatio-temporal fixed point, for  $\epsilon \geq \epsilon_c$

1.  $p_t = 1.0, p_s = 1.0$ . This is the regime where one has a completely random network with the links switching at every iteration. Fig. 1.3-[top-left] shows that the critical coupling strength  $\epsilon_c \approx 0.54$ .
2.  $p_t = 1.0, p_s = 0.65$ . Here links are switched at every time step. However, the probability of these links being spatially random is reduced. Fig. 1.3-[top-right] shows that this decrease in randomness in spatial connections reduces the range of spatiotemporal synchronization, with the critical coupling strength now being  $\epsilon_c \approx 0.62$ .
3. The case of  $p_t = 0.5, p_s = 0.65$  is displayed in Fig. 1.3-[bottom-left] and that for  $p_t = 0.1, p_s = 0.65$  in Fig. 1.3-[bottom-right]. With decreasing  $p_t$ , at fixed  $p_s$ , the critical coupling strength  $\epsilon_c$  increases from  $\approx 0.66$  for  $p_t = 0.5$  to  $\approx 0.91$  for  $p_t = 0.1$ . Namely as the probability of changing links decreases, the range for the spatio-temporal fixed

point decreases. So a more dynamic web of links is more favourable for inducing spatiotemporal regularity in coupled chaotic systems.

Now, we consider low probability of link change, namely a network near the static limit, with  $p_t$  close to zero. The analysis in this regime is complicated by the fact that one obtains a range of critical coupling strengths, with  $\epsilon_c$  being strongly dependent on the initial configuration of links. A deeper understanding is gained by studying the distribution of  $\epsilon_c$ , at fixed  $p_t$  and  $p_s$ , for different initial conditions, as displayed for representative cases in Fig. 1.2.

It is clear from Fig. 1.2 that for the case of  $p_t = 0.0$ , i.e. a static network with quenched links, there is a spread of critical coupling strengths  $\epsilon_c$ , with the range being approximately  $[0.73 : 0.97]$ , and the most probable value being  $\sim 0.85$ . As  $p_t$  increases, for instance when  $p_t = 0.01$ , we observe that the spread of critical coupling strength  $\epsilon_c$  narrows considerably, and the most probable value also shifts to a smaller value. Lastly, for the limiting case of  $p_t = 1.0$ , it is clear that the critical coupling strength  $\epsilon_c$  rapidly converges to a single value. This is a reflection of the “self-averaging” arising from dynamically changing links, as  $p_t$  becomes larger.

Now we analyze the variation of the average critical coupling strength  $\langle \epsilon_c \rangle$  with respect to the probability of link change  $p_t$ . Figs. 1.3 display the average critical coupling strength (in red), the maximum value of critical coupling strength  $\epsilon_{cmax}$  observed (in green) and the minimum value of critical coupling strength  $\epsilon_{cmin}$  observed (in blue). From the plots it is evident that  $\langle \epsilon_c \rangle$  displays a clear trend under increasing  $p_t$ , even at low  $p_t$  when the  $\epsilon_{cmin}$  and  $\epsilon_{cmax}$  values are rather far apart.

### 1.3.1 Interplay of $p_s$ and $p_t$ on spatio-temporal regularity

The next part of our analysis is to uncover the effect of  $p_s$  on the dependence of the critical coupling strength  $\langle \epsilon_c \rangle$  on  $p_t$ . In order to do this, we examine the  $\langle \epsilon_c \rangle$  vs  $p_t$  curves for different values of  $p_s$ , and attempt to fit a suitable functional form to capture the trend.

We explored a power-law fit, given by:

$$\langle \epsilon_c \rangle = \frac{1}{(p_t)^a} + b \quad (1.3)$$

with  $a$  and  $b$  being the fitting parameters.

For the best possible curve fit analysis, we took the datapoints in the range  $p_t = [0.25 - 0.75]$ . Fig. 1.4 shows the data alongside the fitted curve.

The values of the fitting parameters  $a$  and  $b$  are tabulated below:

$p_s$	$a$	$b$
0.5	0.0656857	-0.328514
0.65	0.0724886	-0.384942
0.7	0.07449	-0.400539
0.8	0.0801529	-0.428067
0.9	0.0847064	-0.446896

*Dependence of parameters  $a$  and  $b$  on  $p_s$ :*

Fig. 1.5 shows the variation of fitting parameter  $a$  on  $p_s$ .

Fig. 1.5 shows the variation of fitting parameter  $b$  on  $p_s$ .

### 1.3.2 Synchronization

We now study the degree of synchronization in the system quantitatively through the synchronization error function defined as

$$Z(n) = \frac{1}{N} \sum_{i=1}^N [x_n(i) - x^*]^2 \quad (1.4)$$

averaged over time  $n$  and calculated after transient time. Here  $x^*$  is the fixed point for the logistic map equal to 0.75.

In the results displayed here, the synchronization error is averaged over 10000 time steps, after a transient time of 100 steps for 100 different initial conditions. The value of  $p_s$  is 0.65.

Fig. 1.7-[top] shows the variation of the averaged synchronization error  $\langle Z \rangle$  (in red), the maximum synchronization error  $Z_{max}$  (in green), the minimum synchronization error  $Z_{min}$  (in blue) as a function of coupling strength  $\epsilon$ , for  $p_t = 0$  (i.e. a static network). At low coupling strengths ( $\epsilon \in [0.0 - 0.1]$ ), and at very high coupling strengths ( $\epsilon \geq 0.95$ ),  $\langle Z \rangle$ ,  $Z_{min}$  and  $Z_{max}$  are equal, i.e. different initial conditions yield the same spatio-temporal dynamics. The range of coupling in-between these is of interest as a spread is observed here between  $Z_{max}$  and  $Z_{min}$ , implying that different initial conditions lead to different degrees of synchronization. However, the averaged synchronization error  $\langle Z \rangle$  shows a clear trend, as it decreases with increasing  $\epsilon$ , finally becoming zero at  $\epsilon_c \approx 0.85$ . That is, for  $\epsilon \geq \epsilon_c$  we obtain complete synchronization. Another interesting observation is a dip at around  $\epsilon = 0.2$ , signifying enhanced synchronization around that coupling strength. This is due to the existence of stable 2-cycle over a small range of coupling strengths.

Fig. 1.7-[middle] shows the case of  $p_t = 0.01$ . Now the separation in  $Z_{min}$  and  $Z_{max}$  is negligible for entire coupling range ( $\epsilon \in [0.0 : 1.0]$ ), signifying that almost all initial conditions evolve to same spatio-temporal state, i.e. there exists a global attractor for the dynamics. The dip in  $\langle Z \rangle$  is still discernable at around  $\epsilon = 0.2$ . The bifurcation diagram around this coupling strength is shown in Fig. 1.8.

Fig. 1.7-[bottom] shows the results for  $p_t = 0.5$ . The dip around  $\epsilon = 0.2$  is gone and there is a smooth trend for  $\langle Z \rangle$ . This implies that the 2-cycle at weak coupling is destroyed when the links change too frequently. However at strong coupling the dynamic links stabilize a larger range for the spatiotemporal fixed point.

We have also studied the variation of  $Z$  with respect to  $p_t$ . Fig. 1.9 shows the variation of the averaged synchronization error  $\langle Z \rangle$  (in red), the maximum synchronization error  $Z_{max}$  (in green), the minimum synchronization error  $Z_{min}$  (in blue) as a function of  $p_t$ , for coupling strength  $\epsilon = 0.65$ . It is evident that  $\langle Z \rangle$  decreases as  $p_t$  increases upto a critical point  $p_t \approx 0.54$ , and there onwards is zero till  $p_t = 1.0$ . This implies that if the probability of changing links is higher than  $\sim 0.54$ , one obtains complete synchronization.

A noteworthy trend here is that the separation of  $Z_{min}$  and  $Z_{max}$  rapidly decreases as  $p_t$  increases.

Fig. 1.10 shows the variation of  $\langle Z \rangle$  with changing  $p_t$ , for  $\epsilon = 0.7$ . In this case, the critical point after which complete synchronization is observed is around 0.28. Hence it is evident that at higher coupling strengths larger range of  $p_t$  exhibits complete synchronization.

## 1.4 Average time to reach Synchronization

We define an order parameter  $T_{sync}$ , which represents the time after which the network is completely synchronized. We then study its variation with respect to  $p_t$  and  $\epsilon$  at different values of  $p_s$ . Specifically we calculate the average  $\langle T_{sync} \rangle$ , the maximum time  $T_{syncmax}$  and minimum time  $T_{syncmin}$ .

Figs. 1.11 show the case of  $p_t = 0.01$  and  $p_t = 0.1$ . The separation of the minimum and maximum values of  $T_{sync}$  is large for low  $\epsilon$  which then decreases considerably at higher coupling strengths. Further for large  $p_t$ , i.e. when the links change frequently, the spread in synchronization time narrows considerably. This is a reflection of the self-averaging effect of dynamic links.

We further, explored the trend of  $\langle T_{sync} \rangle$  under variation of  $p_s$ ,  $p_t$  and system size  $N$ . We show representative cases in Figs. 1.12-1.14. It is clear that for smaller system, i.e. low  $N$ , the sudden drop in the time needed to reach synchronization begins at lower coupling strengths  $\epsilon$ .

We have also investigated the dependence of the time needed to reach synchronization  $\langle T_{sync} \rangle$  vs.  $p_t$ . Representative results are displayed in Figs. 1.15-1.17.

### 1.4.1 Intermittent approach to synchronization

The system here mainly exhibits two kinds of dynamics after transience, either it synchronizes to the fixed point completely or it stays chaotic. But here another regime is observed, where the system displays synchronized periods with bursts of unsynchronized behaviour. This is

illustrated by the time-series of a representative case shown in Fig. 1.18. As it can be seen, the system shows almost complete spatiotemporal synchronization around  $t_1 = 2500$  for the first time, but subsequently loses it, synchronizing again around  $t_2 = 4600$ , after which it remains synchronized upto the limits of our simulation time.

We define a parameter  $L_{intermittant}$  which reflects for the time duration of such intermittent behaviour. This is the time between the the first event of near complete spatiotemporal synchronization and the last unsynchronized burst observed. Specifically, without loss of generality, we consider a system synchronized if the synchronization error  $Z < 0.00001$ .

We find the average of this parameter over 100 diifferent initial, and we follow the system up to 5000 iterations. In particular, we study the dependence of the intermittent period on the coupling strength.

Figs. ?? show that there is no intermmitency, i.e.  $L_{intermittant} = 0$ , for the completely chaotic region at low coupling strengths, and the completely synchronized region at high coupling strengths. However, for a range of coupling around the critical coupling strength, the average length of the intermittent period increases and then decreases, reaching a maximum around  $\epsilon_c$ . It is further evident that as the probability of changing links increases, the range of coupling strengths over which this intermittent approach to synchronization is observed, decreases.

Fig. 1.20 shows the dependence of the intermittent period on the probaility  $p_t$  of link change, and a similar qualitative picture is seen here as well.

## 1.5 Generality of Results

In order to gauge the generality of our results, we also analysed a network of Exponential Maps (also known as the Ricker Map). These are given by the dynamical equation:

$$f(x) = x e^{r(1-x)} \quad (1.5)$$

We take parameter  $r$  to be 2.6, where the map is strongly chaotic.

Representative results are shown in Fig. 1.21. Clearly, spatiotemporal synchronization is obtained at coupling strengths  $\epsilon > \epsilon_c$ , where  $\epsilon_c = 0.48$  for  $p_t = 1$ .

Now, for 100 different initial conditions, the variation of  $\langle \epsilon_c \rangle$ ,  $\epsilon_{cmax}$  and  $\epsilon_{cmin}$  with respect to  $p_t$  was calculated, and the results are displayed in Fig. 1.22. It is evident that the qualitative picture is same as in a network of chaotic logistic maps. Namely, we again observe a wider separation between  $\epsilon_{cmax}$  and  $\epsilon_{cmin}$  at very low  $p_t$  (.e. close to the static limit), and this shrinks rapidly as  $p_t$  increases. As before, we also find a smooth decreasing trend for  $\langle \epsilon_c \rangle$  with increasing  $p_t$ . So it is clear that more frequent link changes enhances the range of spatiotemporal synchronization, with the critical coupling strength necessary

to obtain the spatiotemporal fixed point being lower in networks with faster variation in connectivity.

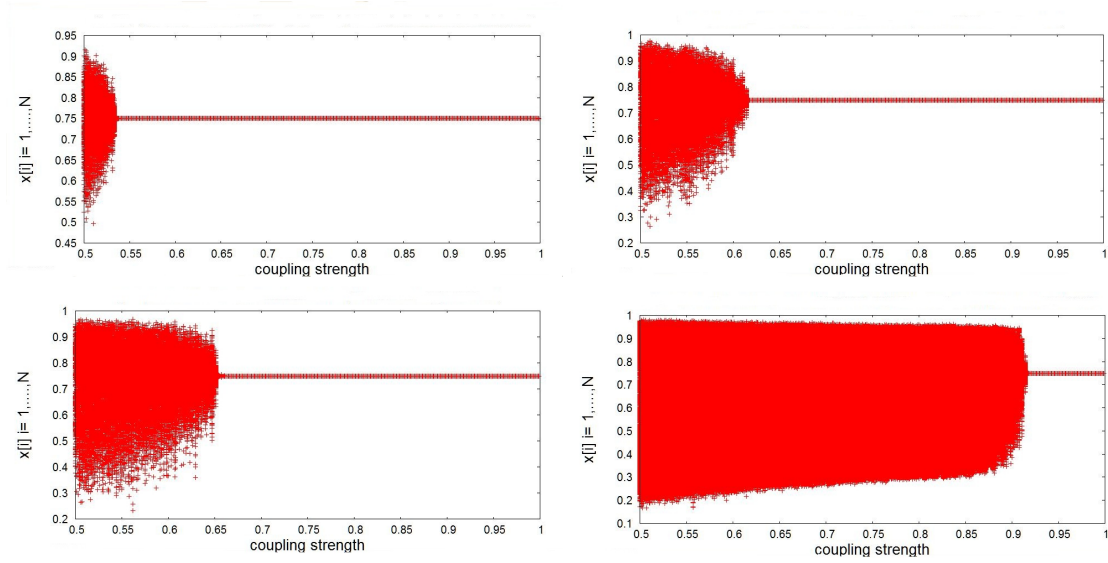


Figure 1.1: State of the system  $x_n(i)$ ,  $i = 1, \dots, N$ , for a network of size  $N = 50$ , with respect to coupling strength  $\epsilon$ . The plot shows 5 superimposed iterates after 2000 transient steps, for 10 random initial conditions.  $p_t = 1.0$  and  $p_s = 1.0$  (top left);  $p_t = 1.0$  and  $p_s = 0.65$  (top right);  $p_t = 0.5$  and  $p_s = 0.65$  (bottom left);  $p_t = 0.1$  and  $p_s = 0.65$  (bottom right).

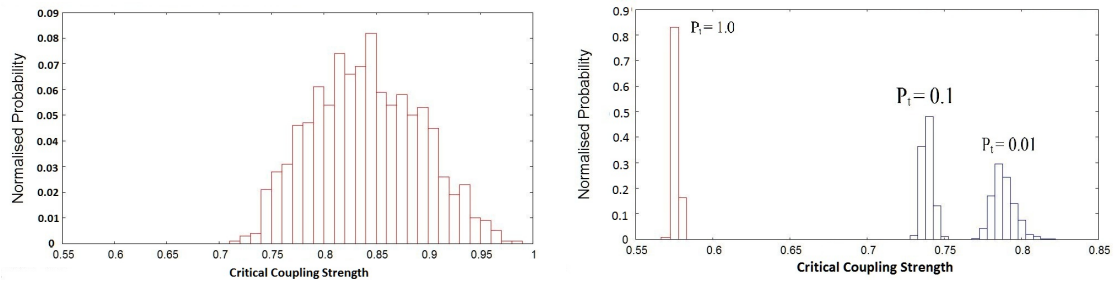


Figure 1.2: Distribution of critical coupling strengths  $\epsilon_c$  obtained for a network of size  $N = 50$  with  $p_s = 0.65$  for 1000 different initial conditions. Here  $p_t = 0.0$  (left);  $p_t = 0.01, 0.1, 1.0$  (right).

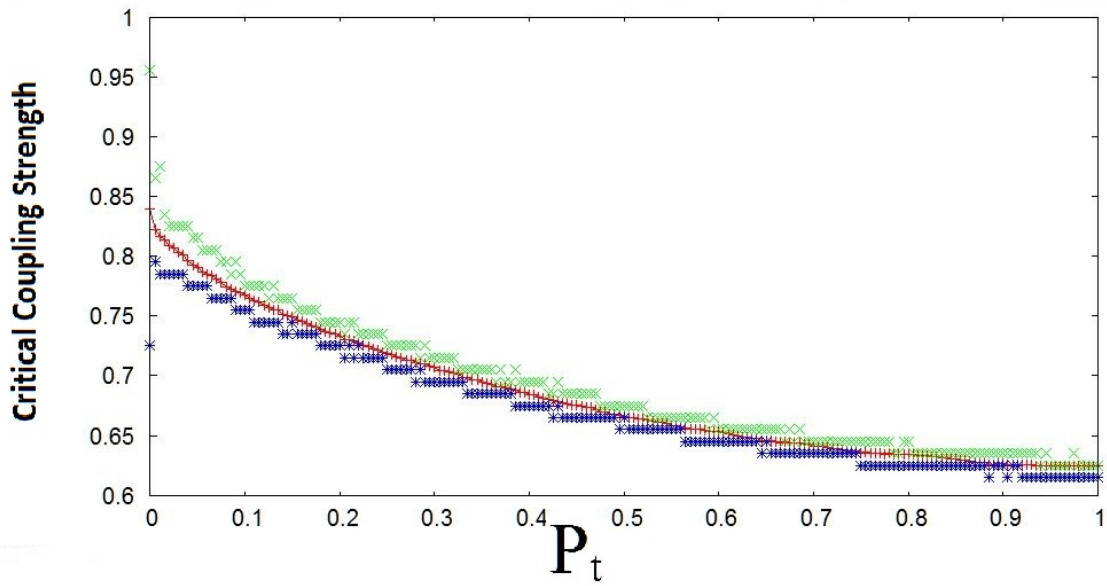


Figure 1.3: Averaged critical coupling strength  $\langle \epsilon_c \rangle$  with respect to the probability of link change  $p_t$ , in a network of size  $N = 50$ , with  $p_s = 0.65$ .

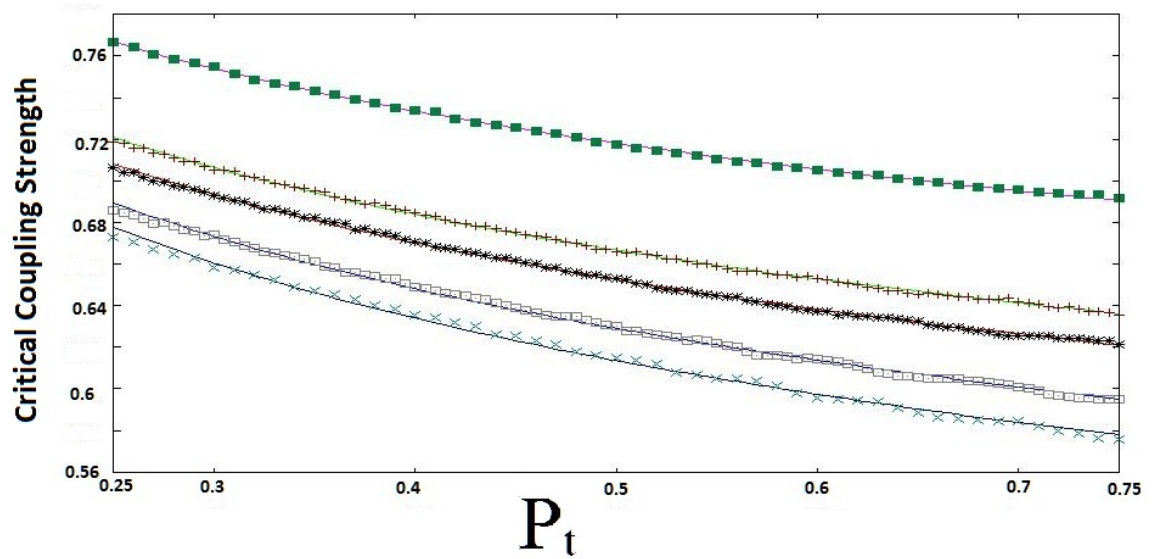


Figure 1.4: Variation of the average critical coupling strength  $\langle \epsilon_c \rangle$  on the probability of link change  $p_t$ , for fraction of random links  $p_s$  equal to (from top to bottom): 0.5; 0.65; 0.7; 0.8; 0.9.



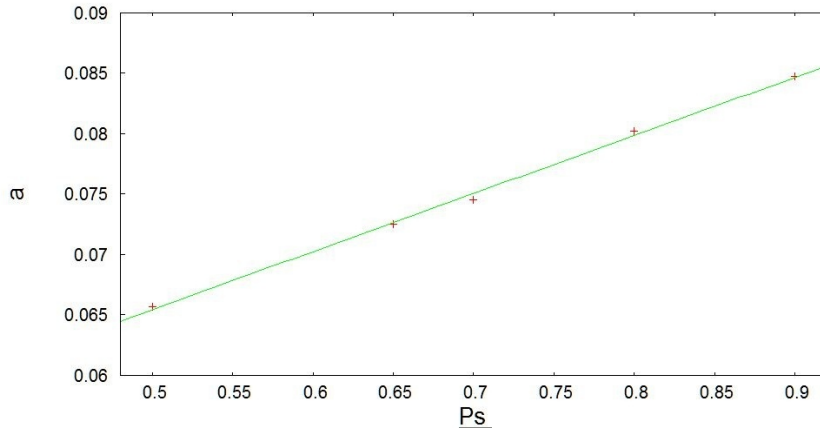


Figure 1.5: Plot of parameter  $a$  (see Eqn. 1.3) vs  $p_t$ . The best fit line has slope equal to 0.0480409 (with standard deviation equal to 2.764%) and intercept equal to 0.0413957 (with standard deviation equal to 2.319%)

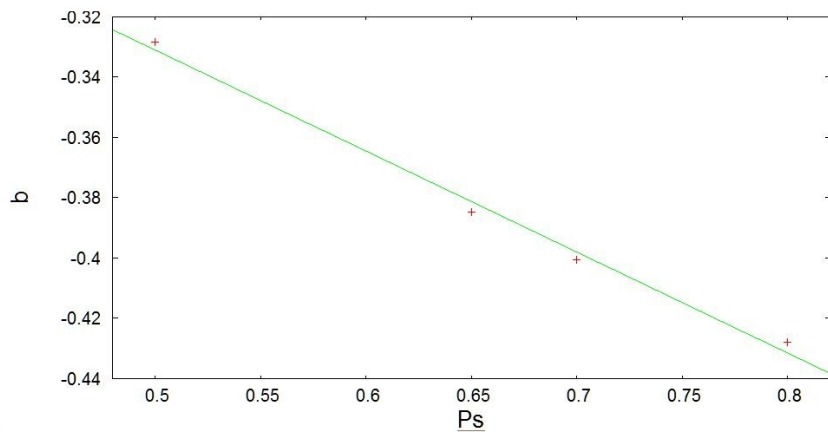


Figure 1.6: Plot of parameter  $b$  (see Eqn. 1.3) vs  $p_t$ . The best fit line has slope equal to 0.334595 (with standard deviation equal to 6.018%) and intercept equal to 0.0413957 (with standard deviation equal to 8.25%)

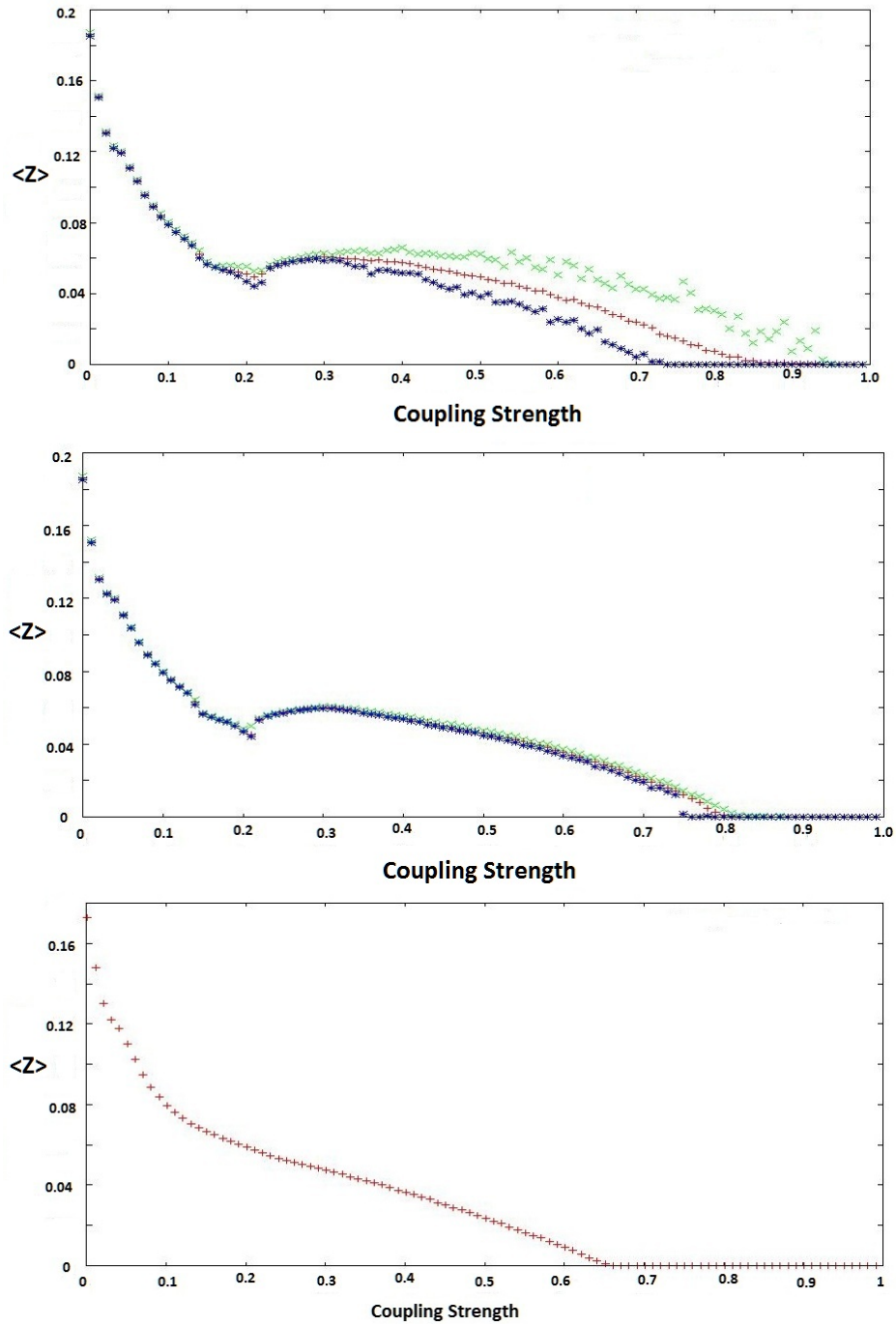


Figure 1.7: variation of the averaged synchronization error  $\langle Z \rangle$  (in red), the maximum synchronization error  $Z_{max}$  (in green), the minimum synchronization error  $Z_{min}$  (in blue) as a function of coupling strength  $\epsilon$ , for  $p_t = 0$  (i.e. a static network) [top];  $p_t = 0.01$  [middle];  $p_t = 0.5$  [bottom].

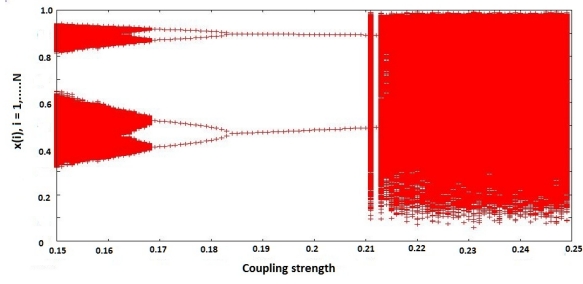


Figure 1.8: Bifurcation diagram showing the state of the system  $x_n(i), i = 1, \dots, N$ , for a system of size  $N = 50$ , with respect to coupling strength  $\epsilon$ .

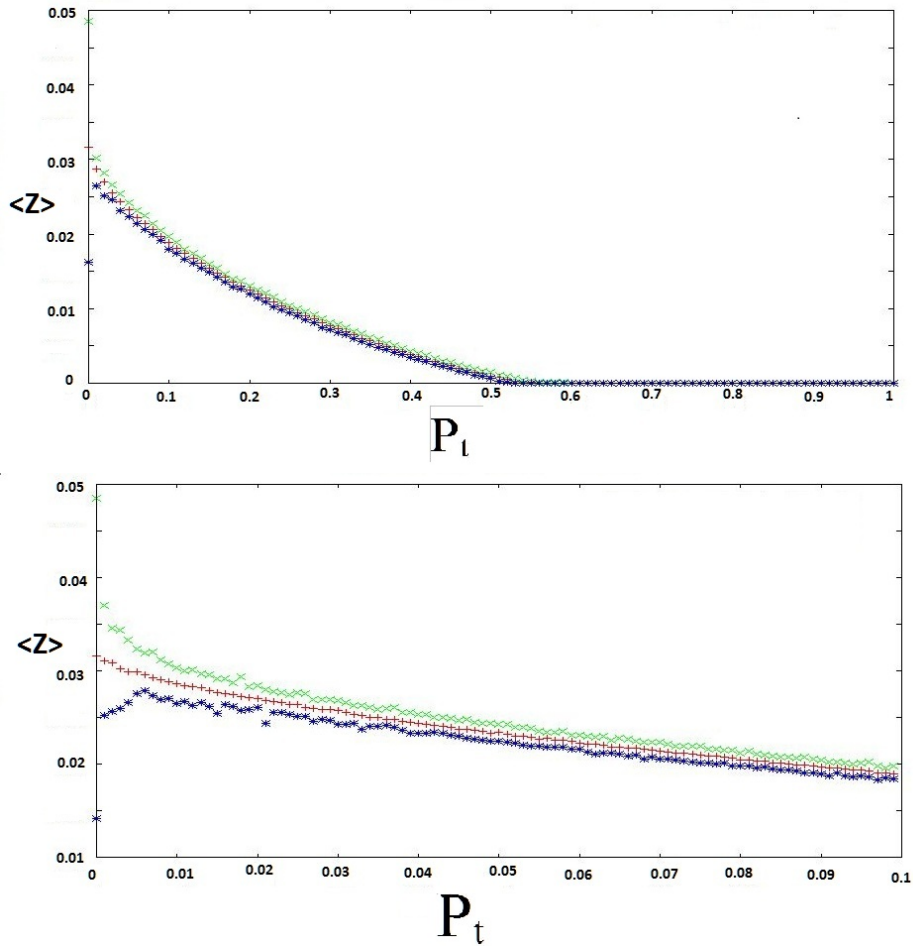


Figure 1.9: variation of the averaged synchronization error  $\langle Z \rangle$  (in red), the maximum synchronization error  $Z_{max}$  (in green), the minimum synchronization error  $Z_{min}$  (in blue) as a function of  $p_t$ , for  $\epsilon = 0.65$ .

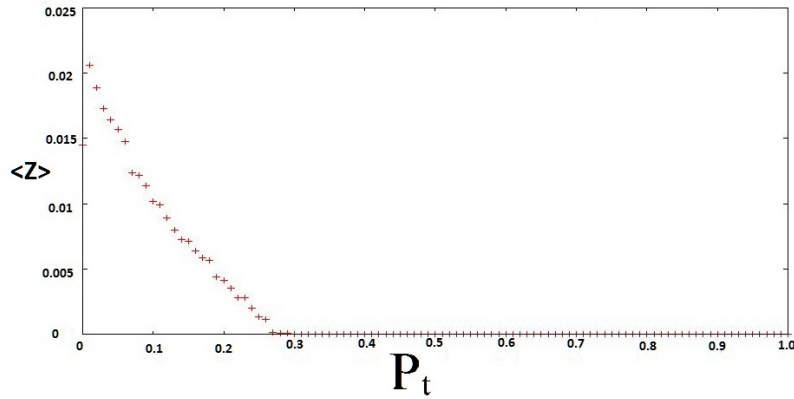


Figure 1.10: variation of the averaged synchronization error  $\langle Z \rangle$  (in red), the maximum synchronization error  $Z_{max}$  (in green), the minimum synchronization error  $Z_{min}$  (in blue) as a function of  $p_t$ , for  $\epsilon = 0.7$ .

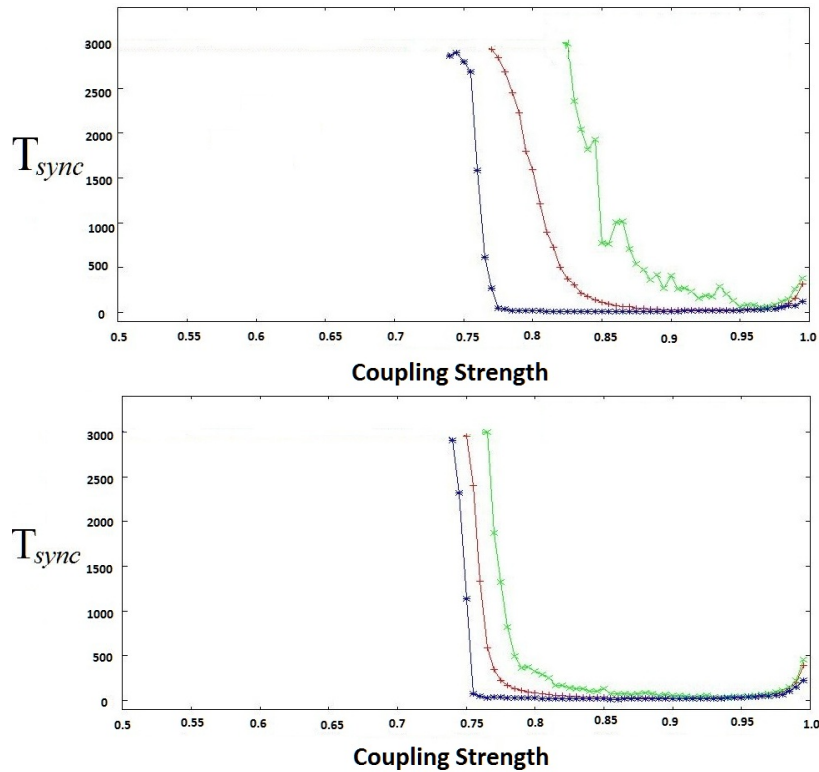


Figure 1.11: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , the maximum time  $T_{syncmax}$  and minimum time  $T_{syncmin}$  with respect to coupling strength  $\epsilon$ . To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here the size of the system is  $N = 50$ ,  $p_s = 0.65$ , and  $p_t = 0.01$  [top];  $p_t = 0.1$  [bottom].

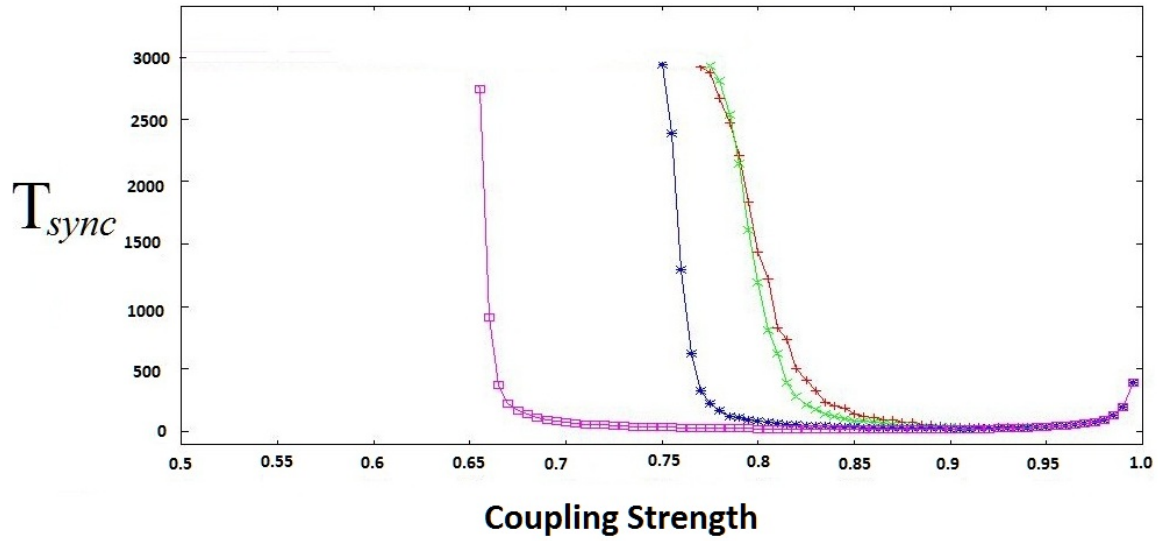


Figure 1.12: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$  the maximum time  $T_{syncmax}$  and minimum time  $T_{syncmin}$  with respect to coupling strength  $\epsilon$ . To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $p_s = 0.65$ ,  $N = 50$  and  $p_t = 0.01; 0.02; 0.1; 0.5$ .

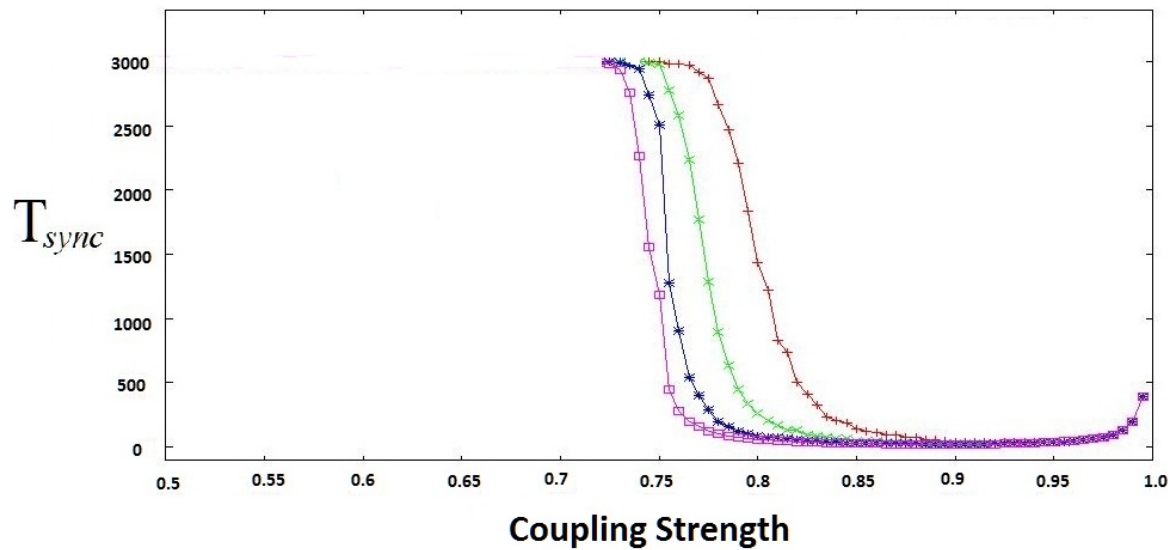


Figure 1.13: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , with respect to coupling strength  $\epsilon$ . To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $N = 50$ ,  $p_t = 0.01$ , and  $p_s = 0.65, 0.75, 0.85, 1.0$ .

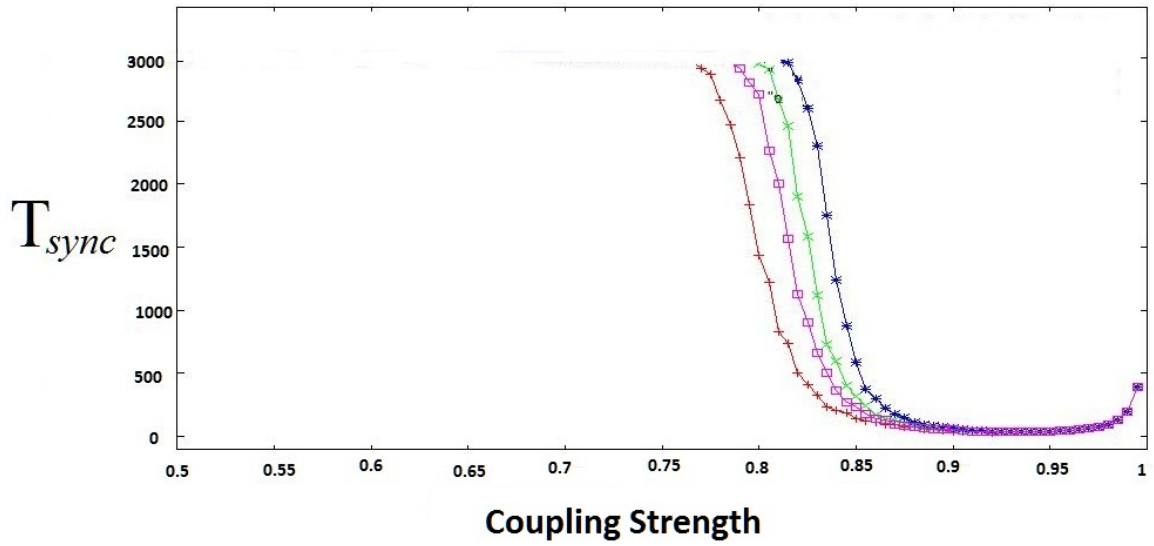


Figure 1.14: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , with respect to coupling strength  $\epsilon$ . To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $p_t = 0.01$ ,  $p_s = 0.65$  and  $N = 50, 75, 100, 150$ .

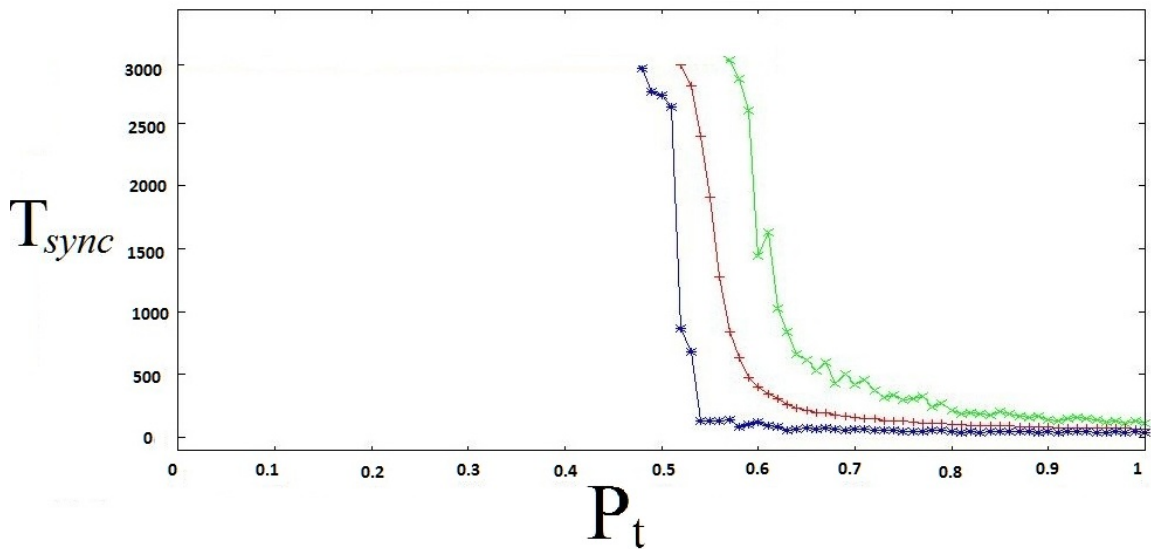


Figure 1.15: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , the maximum time  $T_{syncmax}$  and minimum time  $T_{syncmin}$  with respect to probability  $p_t$  of link change. To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $\epsilon = 0.65$ ,  $p_s = 0.65$ .

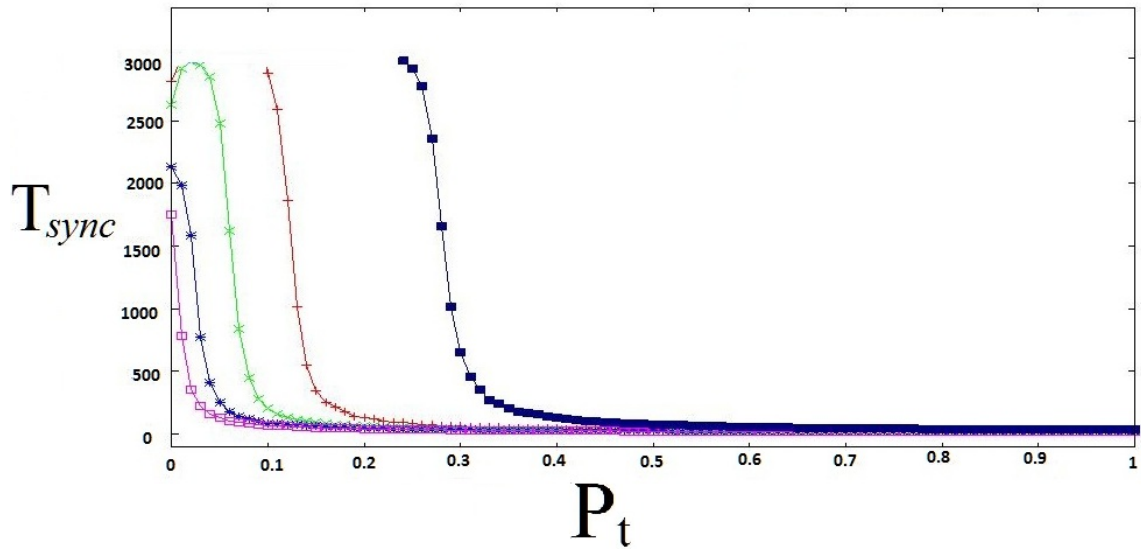


Figure 1.16: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , with respect to probability  $p_t$  of link change. To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $\epsilon = 0.75$ ,  $N = 50$ ;  $p_s = 0.5, 0.65, 0.75, 0.85, 1.0$ .

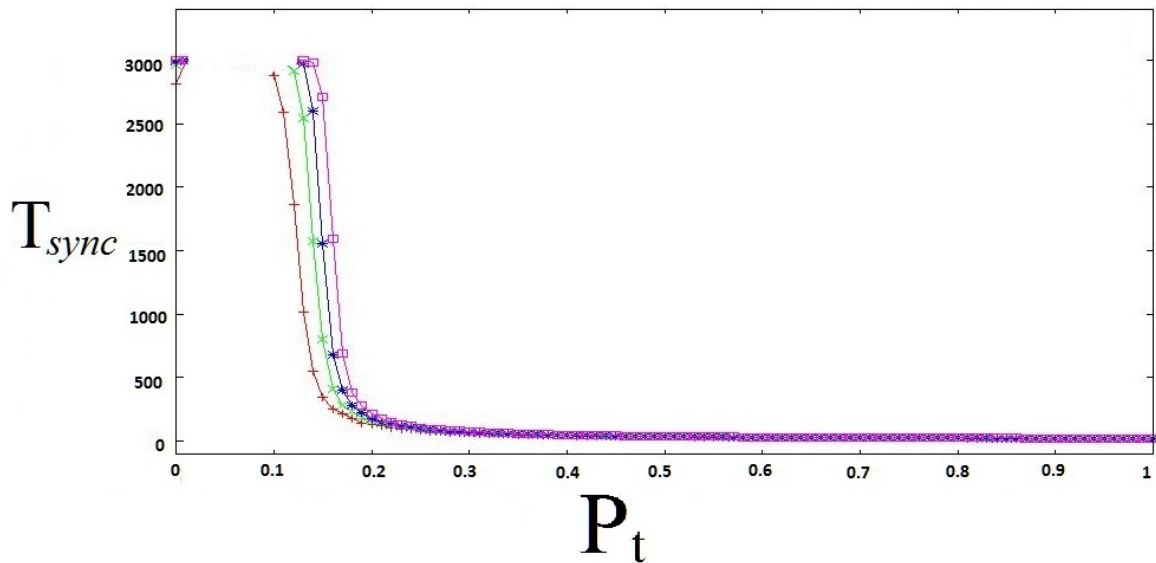


Figure 1.17: Variation of the average time needed to reach the synchronized state  $\langle T_{sync} \rangle$ , with respect to probability  $p_t$  of link change. To calculate  $\langle T_{sync} \rangle$  we average over 3000 time steps and 500 different initial conditions. Here  $\epsilon = 0.75$ ,  $p_s = 0.65$ ;  $N = 50, 75, 100, 150$ .

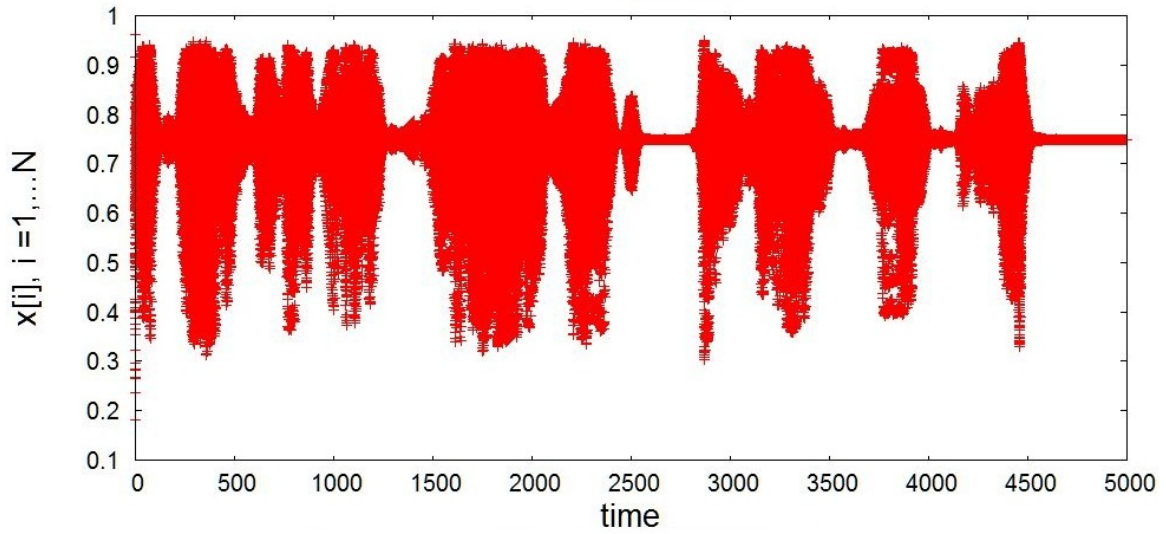


Figure 1.18: Time evolution of a system of coupled chaotic logistic maps, with  $p_t = 0.01$ ,  $p_s = 0.65$ ,  $\epsilon = 0.78$  and  $N = 50$ .

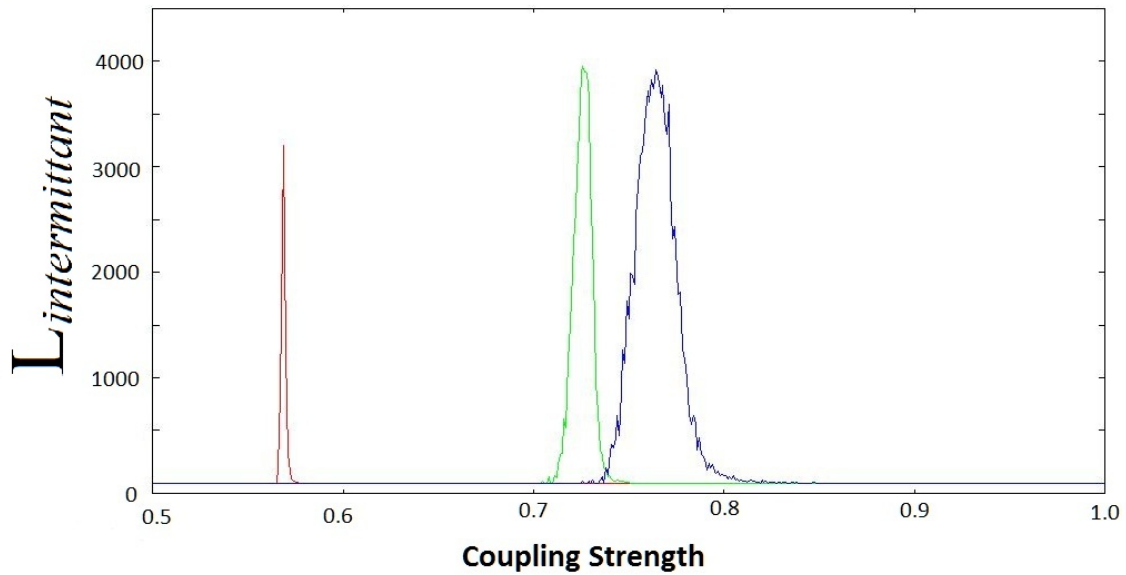


Figure 1.19:  $L_{intermittent}$  vs. Coupling Strength for the case of local link changes, with fraction of random links  $p_s = 0.8$ , link switching probability  $p_t = 0.01$ (red);  $0.1$ (green);  $1.0$ (blue). Here network size  $N = 100$ , and  $L_{intermittent}$  is obtained by averaging over 100 realizations.



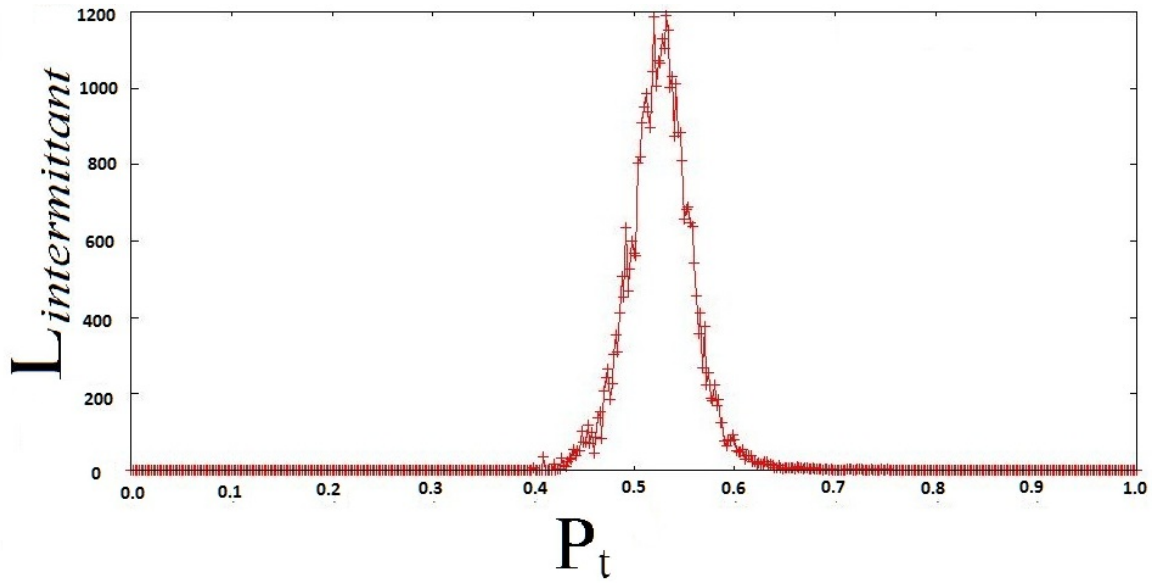


Figure 1.20:  $L_{intermittant}$  with respect to the probability  $p_t$  of link change, for a system of size  $N = 50$ , with  $p_s = 0.65$  and  $\epsilon = 0.65$ , averaged over 100 realizations and system followed up to 2000 iterations.

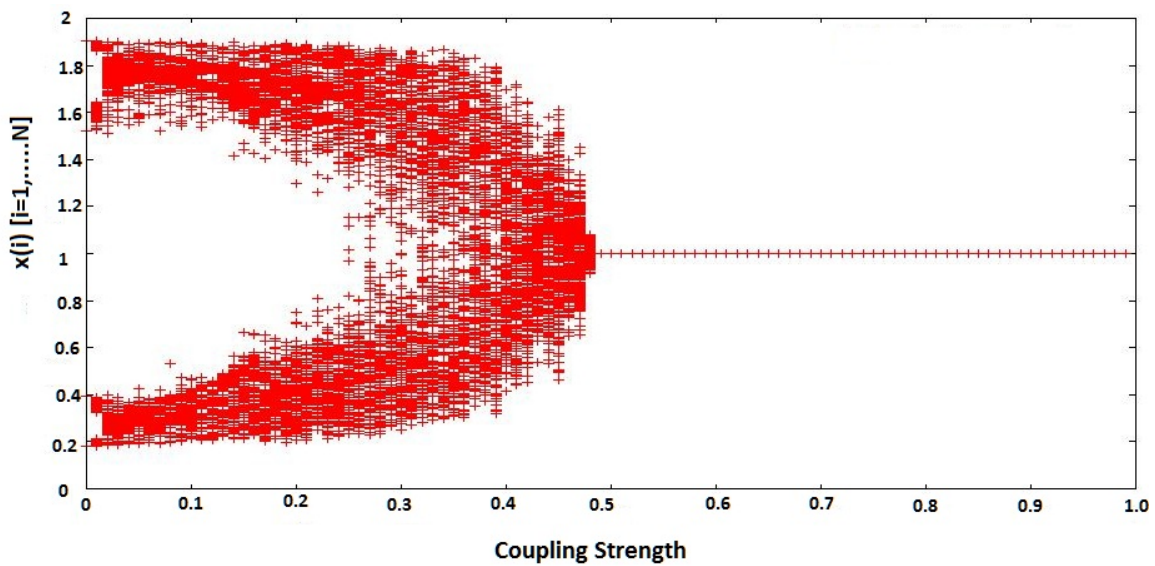


Figure 1.21: Variation of the state of the system  $x_n(i)$  ( $i = 1, \dots, N$  and  $n = 1, \dots, 5$  after a transient time of 1000 iterations), with respect to coupling strength  $\epsilon$ , at  $p_t = 1.0$ . The system size  $N = 50$ , and probability of spatial randomness  $p_s$  is 0.65.

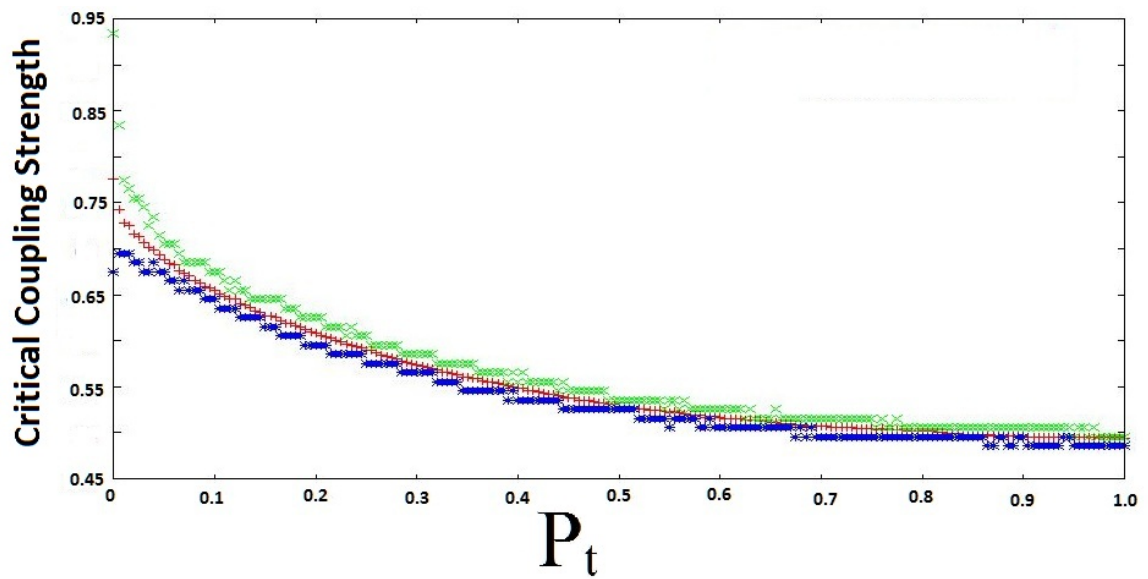


Figure 1.22: Variation of the average critical coupling strength necessary to obtain the synchronized state  $\langle \epsilon_c \rangle$ , the maximum coupling strength  $\epsilon_{cmax}$  and the minimum coupling strength  $\epsilon_{cmin}$ , with respect to probability  $p_t$  of link change. Here  $p_s = 0.65$  and  $N = 50$ .



## Chapter 2

# A Cellular Automata Model of disease spread on a 2-Dimensional lattice

### 2.1 Introduction

How does a disease spread in a population? A question which has been greatly explored over the years. Various cases of epidemics and their phenomenological descriptions have been studied by the scientists.[18, 19, 20]

Mathematically, epidemiological models have been given to understand the dynamics of infectious disease.[21, 22] In a paper by Hethcote (1976) a well known model for disease progression: the SIRS cycle is explained. This model fits appropriately for diseases such as small pox, tetanus, influenza , typhoid fever and cholera[23]. Recently, a study by Ozcaglar (2012) has provided a review of earlier study on modeling different aspects of tuberculosis dynamics.[24]

Here in this work we focus on disease progression described by cellular automata model of SIRS cycle. Based on this model, work has been done previously to study the spread of infection within a population where the interactions are described by small world network.[25, 26, 27]

Rhodes and Anderson (1996) presented a lattice-based epidemic model of a non-fatal communicable disease in a mobile host population in which they observed novel dynamical behaviour.[28]

In this work we consider a lattice-based epidemic model where the population is represented by a 2-D lattice with the nodes representing the individuals and the individual follow the SIRS cycle of disease progression.

## 2.2 Model

We consider a population spread to be represented by a 2-D lattice of dimensions (MxN), where every node has 4 neighbors and with open boundaries. We further consider at the individual level the disease progresses in accordance with the well-known epidemiological model : *the SIRS cycle*.

The SIRS cycle can be elaborated in following steps : at the outset an individual is *susceptible* to infection (a stage denoted by S); on infection with other infected people, the individual moves to *infectious* stage (I). This is followed by a *refractory* stage (R), in this stage the individual becomes immune to disease and also does not infect others. But this immunity is temporary as the individual becomes susceptible again after some time interval.[27] Here, we impose a condition that *a susceptible(S) will become infected(I) if one or more of any of its neighbours is infected*.

**Mathematically, the model is explained as follows:**

Time is taken in discrete steps. Each element is characterized by a time counter  $\tau_{ij}(t) = 0, 1, \dots, \tau_I + \tau_R = \tau_0$ , describing its phase in the cycle of the disease.[25] So at any time  $t$ , if  $\tau_{ij}(t) = 0$ , then individual at site  $(i, j)$  is susceptible, if  $1 \leq \tau_{ij}(t) \leq \tau_I$  then it is infected and if  $\tau_{ij}(t) > \tau_I$  it is in refractory stage.

For,  $\tau_{ij}(t) \neq 0$  the dynamics is given by  $\tau_{ij}(t+1) = \tau_{ij}(t) + 1$ , but when the cycle reaches the end the individual becomes susceptible again which means if  $\tau_{ij}(t) = \tau_0$  then,  $\tau_{ij}(t+1) = 0$ .

**Condition for infection:**

Further, if  $\tau_{ij}(t) = 0$ , (the individual is susceptible), then  $\tau_{ij}(t+1) = 1$ , if  $1 \leq \tau_{xy}(t) \leq \tau_I$  where  $xy \in \{(i-1, j); (i+1, j); (i, j-1); (i, j+1)\}$  which means the individual becomes infected if one or more of its nearest neighbours is infected.

## 2.3 Infection Spread: How it actually looks in time?

We consider different initial configurations of the 2-D lattice. Then, based on the above explained model we studied the spread of infection and observed the changes in the state of individuals in the population with time. This was done through a simple visual study of the 2-D lattice.

We fixed the parameters to be;

$\tau_I = 4$ ;  $\tau_R = 9$ ;  $\tau_0 = 13$  and lattice-size = 100x100.

The various scenarios that we explored are as follows:

- **All individuals are susceptible to infection.** [  $\tau_{ij} = 0$  ]

- **Case 1:** 1 infected individual at the center of the lattice. [  $\tau_{50,50} = 1$ ]. This can be thought of as a control for this analysis as the results of this case can be intuitively understood.  
Fig. 2.1, exhibits that as time progresses the infection starts from the central seed and spreads symmetrically. At the individual level the disease cycle also progresses and so the phase of dynamical unit changes with time.  
The interaction of susceptible individuals with the infected ones is a key factor in the infection spread. As it takes place only at the outer boundary of the pattern so the infection ultimately gets removed from the population.
- **Case 2:** 1 infected individual at the center of the lattice (but permanently infected) [  $\tau_{50,50} = 1$  always]. (Fig- 2.2) Same as the previous case, but a repeating pattern due to the permanent infection is seen.
- **Case 3:** 2 infected individuals at (50,25) & (50,75) [  $\tau_{50,25}; \tau_{50,75} = 1$ ]. From fig. 2.3 it can be clearly seen that even if the infection arising from one location interact with an other infection, the result is a symmetrical pattern.
- **Case 4:** 2 individual always infected and located symmetrically at (50,25) & (50,75) [  $\tau_{50,25}; \tau_{50,75} = 1$ ](Fig- 2.4).

After the control study, we now incorporate our model on a rather realistic case by introducing randomness to the initial configuration of the 2-D lattice.

- **Individuals are randomly distributed as susceptible with [  $\tau_{ij} = \tau_S = 0$ ], their fraction is represented by  $S_0$  and as refractory with  $\tau_{ij} = \tau_R = (\tau_I + 1)$ , their fraction is represented by  $R_0$ .**

1 infected individual at the center of the lattice [  $\tau_{50,50} = 1$ ], ( $S_0$ : 0.5;  $R_0$ : 0.5).

Fig 2.5 shows interesting results, the infection was only initial but as time progressed a continuously emerging infection pattern is seen.

**For this case, a show-reel of infection spread**

Time : t=0 to t=35 . (Zoomed in the center).

Similar results were obtained for the case when the individuals in R phase ( $\tau_R$ ) will have a randomly chosen phase from  $[(\tau_I + 1), \tau_0]$ .

## 2.4 Quantifying the infection in the population

Next, we discuss the possibility of quantifying the spread of infection in the population. For this we define a parameter  $I_t$  which represents the fraction of infected individual in the population at time 't'.

$$I_t = \frac{\text{Total number of infected individuals}}{\text{Total number of individuals}} \quad (2.1)$$

Similarly we also define  $S_0$  and  $R_0$  to be the initial fraction of Susceptible and Refractory individuals respectively.

An important observation from the visual study was that not always does one see infection being sustained in the population. Meaning, for a lot of cases the infection gets removed entirely from the population with time.

The infection spread depends on infected individual coming in contact with a susceptible individual. So, for a random initial configuration of S-R population the infection can either progress or not.

### 2.4.1 Histogram analysis

As per the above defined parameter, non-zero  $I_t$  will signify that infection stays in the population. At this point an analysis is required that gives an idea about the frequency of such non-zero  $I_t$  events. Fig- 2.6, shows the histogram analysis for 2 configuration  $[S_0:R_0]$

- 0.5:0.5] (top) &  $[S_0:R_0 - 0.75:0.25]$  and clearly it can be seen that a non-zero frequency is observed only around 2 region in  $I_t$ . So, if  $I_t = 0$ , then infection gets removed from the population. Also, if the infection do stays in the population with time ( $I_t \neq 0$ ), then a small range for non-zero  $I_t$  signifies that to a great extent the spread pattern for different realizations remains the same.

### 2.4.2 Dependence of infection spreading on the fraction of susceptibles in the population

For fixed  $\tau_I$  (4) and  $\tau_0$  (13) measurement of  $I_t$  (fraction of infect individuals on the lattice averaged over 'n' realizations) were done for the complete range of  $S_0$  (Initial fraction of susceptible individuals)  $[0,1]$ . This analysis gave insight about the influence of population type (distribution of susceptible and refractory individuals) on infection spread. Two major methods of defining the initial state/phase of individuals in the lattice were employed. In both the methods, the initial phase of 'S' population was  $\tau_{ij} = 0$ , but the 'R' population can be assumed to exist in following ways:

- Same phase( $\tau_{ij} = \tau_I + 1$ ).
- Randomly different phase( $\tau_{ij} =$  randomly chosen from  $[\tau_I + 1, \tau_0]$ ).

Fig - 2.7, shows the variation of  $I_t$  with initial  $S_0$  for the two cases discussed above.

### 2.4.3 Presenting the arguments to rationalize broad trends

In this section we discuss the broad trends seen in this study. The fig.2.8 shows the variation of  $I_t$  (fraction of infected individuals) over the whole range of  $S_0$  (Initial fraction of Susceptible individuals in the population). Here, the key assumption taken in the analysis is that all the individuals in refractory period initially would have same phase ( $\tau_R = \tau_I + 1 = 5$ ).

As seen clearly,  $I_t$  remains zero at low  $S_0$  in the range  $\approx (0,0.15)$  and also near  $S_0 \approx 1$ . For the in between range one see a continuously increasing and then decreasing trend which peaks around  $S_0 \approx 0.65$ . The spread of infection depends on basic level on infected individuals being in contact of a susceptible one, so it can be reasoned that at low  $S_0$  the chances of this is fairly low so asymptotically the infection eventually gets removed from the population. When there are reasonable number of susceptible individuals in the population, it is seen that asymptotically infection stays in the population. The increasing trend in the range  $S_0 : (0.15,0.65)$  gives an indication that more and more realizations (initial population conditions) are now leading to infection spread. The maxima of this variation comes around a value  $I_t \approx 0.25$ , which is fairly close to 0.28 value we found out in the histogram analysis (this is the value of  $I_t$  observed for a realization leading to infection spread asymptotically).



It means that a great number of realizations are resulting in infection spread.

A decreasing trend in the value of  $I_t$  is seen at higher  $S_0$  from here on which ultimately goes to zero near Initial  $S_0 = 1$ . The colored plots shown in the beginning gives a better idea about this kind of situation. Consider the case where initially all the individuals are susceptible to the infection and an individual in the center is infected, here one can see that the infection does spread but ultimately gets removed from the population. Also, the animation shown in the beginning clearly indicates the need of refractory individuals in the spreading of infection. When there are not many refractory individuals that complete there cycle to again become susceptible, the infection does spread but asymptotically it will get removed and this infection process will not be repeated.

Hence, it can be said that for the infection to stay in the population a well mixed population is required with reasonable number of both susceptible and refractory individuals.

#### 2.4.4 Checking the consistency of results

##### Different lattice sizes

It is important to check whether these results depend on the lattice size. From Fig- 2.9 it is clear that the size of lattice does not influence the infection spread both qualitatively and quantitatively.

##### Time-averaging results

Also the results obtained here are for a fixed time ( $t= 200$ ). But, it becomes crucial to check the time averaged results for this model as the results may vary in time as well.

So, taking the time average for the range  $t = [200,300]$ , with fixed  $\tau_I$  (4) and  $\tau_0$  (13), infection seed at the center, 40x40 lattice ,and same phase ( $\tau_{ij} = \tau_I + 1$ ) for Refractory fraction of population.

From 2.10, it is clear that even on time averaging the variation curve is showing the same trend, hence the analysis at a particular time yields same results as that with time average.

##### Random Infection seed

Another essential component of this analysis would be the location of initial infection seed. Since, it is the source of disease spread it becomes necessary to check the validity of these results for a random initial infection.

Fig -2.11, clearly points out that a random infection seed only changes the origin of the pattern. From fig - 2.12, 2.13 it can be seen that if the infection seed is random present at any position in the lattice, the variation of  $I_t$  over the range of  $S_0$  remains qualitatively same as that for infection seed at center of the lattice. Also,  $I_t$  remains invariant even in this situation, shown in Fig- 2.14.

### 2.4.5 Dependence on the dynamical characteristics of the disease cycle( $\tau_I$ ; $\tau_R$ ; $\tau_0$ )

The SIRS cycle itself plays a crucial role in the spread of the disease. The next part of analysis focus on this interplay between the SIRS cycle and infection spread. According to our model, out of three compartments of SIRS cycle, susceptible is fixed ( $\tau_S = 0$ ), but the other two can be changed. And taking different  $\tau_I$  and  $\tau_R$ , the infection spread analysis was done.

Fig. 2.15 shows that when a infection spreads the pattern formed is similar looking although as the infection and refractory periods are different, one see quantitatively different pattern.

From Fig- 2.16 (exhibit the case when R population is having a fixed same phase) it is clearly seen that the variation of  $I_t$  with  $S_0$  shows a high dependence on the ratio  $\frac{\tau_I}{\tau_R}$ . For a case when

$\frac{\tau_I}{\tau_R} < 1$  [ $\tau_I = 4, \tau_R = 9$ ] & [ $\tau_I = 4, \tau_R = 9$ ], a similar variation is observed with  $I_t$  zero at high and low  $S_{fraction}$  and in between range forming a smooth peak. Here, a noteworthy point is even when the actual cycle length changes the variation curve does not changes much.

When,  $\frac{\tau_I}{\tau_R} = 1$  [ $\tau_I = 4, \tau_R = 4$ ] & [ $\tau_I = 9, \tau_R = 9$ ] a symmetrical variation curve is seen and irrespective of total cycle length, both lead to exactly same result, both qualitatively and quantitatively.

An interesting case arises when  $\frac{\tau_I}{\tau_R} > 1$  [ $\tau_I = 9, \tau_R = 4$ ], in this case one observe a high and constant  $I_t$  value for the lower range of  $S_0$  upto  $\approx .0.3$  and then it smoothly goes to zero as  $S_0$  reaches 1.0.

The same analysis when done for the case of R population having randomly different phase is shown in Fig- 2.17. Here, it can be clearly seen that for fixed disease cycle length ( $\tau_0 = 13$ ) as the period of infection ( $\tau_I$ ) increases the slope of  $I_t$  vs.  $S_{fraction}$  also increases. It indicates that for a population having individuals in random phases in disease cycle will qualitatively remains the same with changing infection period ( $\tau_I$ ), although the fraction of infected individuals would be greater for larger  $\tau_I$ .

### 2.4.6 Changing the heterogeneity in the initial population

Here we have considered two basic initial configuration of population, namely R population having a fixed same phase and R population having randomly different phase. Now, consider a case where the population is in between these two cases, means the refractory individuals in the population are having phases neither completely random nor completely fixed to same value.

We adopt two methods to achieve such configuration:

- **Mixture of uniform and non-uniform sub-populations:** We define a parameter  $\eta$  which represents the fraction of R population having randomly different phases initially and similarly, we can also say that  $(1 - \eta)$  represents fraction of R population having a fixed phase initially ( $\tau_R = \tau_I + 1$ ).

Fig- 2.18 exhibits the change in the variation curve as  $\eta$  and hence the initial configuration changes. It can be clearly seen that as the transition takes place from one extremal initial condition (all R individuals in same phase) to the other (all R individuals in randomly different phases) the variation curve of  $I_t$  gradually changes its form.

- **Varying the range of phases:** We consider that the initial phase of individuals in R compartment of SIRS cycle can be any integer from the range  $\chi$ . This range can be taken to be anything from  $[\tau_I + 1, \tau_R]$  (completely random phases) to  $[\tau_I + 1, \tau_I + 1]$  (completely fixed and same phase).

First we perform the analysis by taking the range  $\chi$  with fix lower bound  $\tau_I + 1$  and different upper bounds. Fig- 2.19 exhibits the variation curves for different  $\chi$ : [5,5]; [5,7]; [5,9]; [5,11]; [5,13]. It can be clearly seen that as the transition takes place from one extremal initial condition (all R individuals in same phase) to the other (all R individuals in randomly different phases) the variation curve of  $I_t$  gradually changes its form.

Another way of altering the range  $\chi$  would be to fix the upper bound at  $\tau_R$  and take different lower bounds. Fig- 2.20 exhibits the variation curves for different  $\chi$ : [5,13]; [7,13]; [9,13]. Here, shortening the range  $\chi$  lead to decrease in  $I_t$  but the qualitatively the variation curve remains the same and for  $\chi$  close to end of cycle  $I_t$  is zero in the entire  $S_0$  range: [0,1]. Hence, we can conclude that when the initial phases of refractory individuals are taken more towards a value at the end of the disease cycle then infection gets removed from the population.

The above done analysis basically covers two distinct senarios where the refractory individuals initially have same phase and randomly different phases. A comparison can be done between the two by considering the randomly different phase situation with its mean at say, 9 (median of refractory period[5,13]) and the same phase situation at initial  $\tau_R = 9$ . From fig.- 2.21, it can be seen that both these senarios are actually distinct, where the randomly different phase situation has the continuously decreasing variation curve and the same phase situation ( $\tau_R = 9$ ) has a variation curve qualitatively similar to same phase with  $\tau_R = 4$  but with considerably low  $I_t$  peaking at a lower value of  $S_0$ .

## 2.5 Discussions and Summary

Here we discuss broadly the model and its analysis by summarising the key ideas and results. Based on the cellular automata model of SIRS cycle disease progression[25] we considered a population represented by a 2-Dimensional lattice. Coupling was introduced in the system by putting the condition for infection that if an individual comes in contact with an infected individual then it will become infected.

To get an idea of the spread of infection visually we took different initial population scenarios and observed with time how the state of individuals changes. We found out that for a completely susceptible population an infection does not give rise to permanent infection although the infection does spread but ultimately gets removed from the population. A permanent infection seed does lead to greater and permanent infection spread in the population. All of which was intuitively understandable, next we considered a situation where individuals are both in susceptible and refractory phase. Here, the population is randomly distributed and an interesting observation was that even for an infection seed put only initially one could see a permanent infection spread pattern.

Now, we quantified the infection spread by defining a parameter  $I_t$  which represented the fraction of infected individuals in the population. A key observation was that on fixing the fraction of susceptible and refractory individuals if we take different random realizations then not all realisations lead to permanent infection spread. Depending on the  $S_0$  and  $R_0$  the frequency of permanent infection spread also changes.

We next looked at the variation of  $I_t$  over the entire range of  $S_0$ , this was done for two scenarios, for refractory individuals in same phase initially and in randomly different phase. Contrasting trends were observed as for the randomly different phase a continuously decreasing trend was seen and for same phase situation a curve was seen which increased continuously and after a point starts to decrease continuously, at the extremes zero infection was observed.

The analysis done till now was at a particular time, so by taking a time average of  $I_t$  we checked that whether it is time dependent and the results of this analysis suggested that the trends here does not change with time. Also, we checked proved the consistency of the results for different lattice size and random infection seed situation.

The system here showed strong dependence on the disease cycle, the change in variation curve for different infection period indicated that for the situation where Refractory individuals are in same phase initially the ratio  $\frac{\tau_I}{\tau_R}$  decides the trend qualitatively. Although for the situation where Refractory individuals are in randomly different phase initially only quantitative change occur in the variation curve.

Next we considered a more general scenarios where the randomness in the phases of Refractory individuals is not complete. We took two approaches, in one case the randomness was changed by changing the fraction of individuals with randomly different phases in R and

other case was shortening the range of randomness in phases. Both theses analysis lead to the conclusion that the variation curve transitions from one case to other in a smooth fashion.

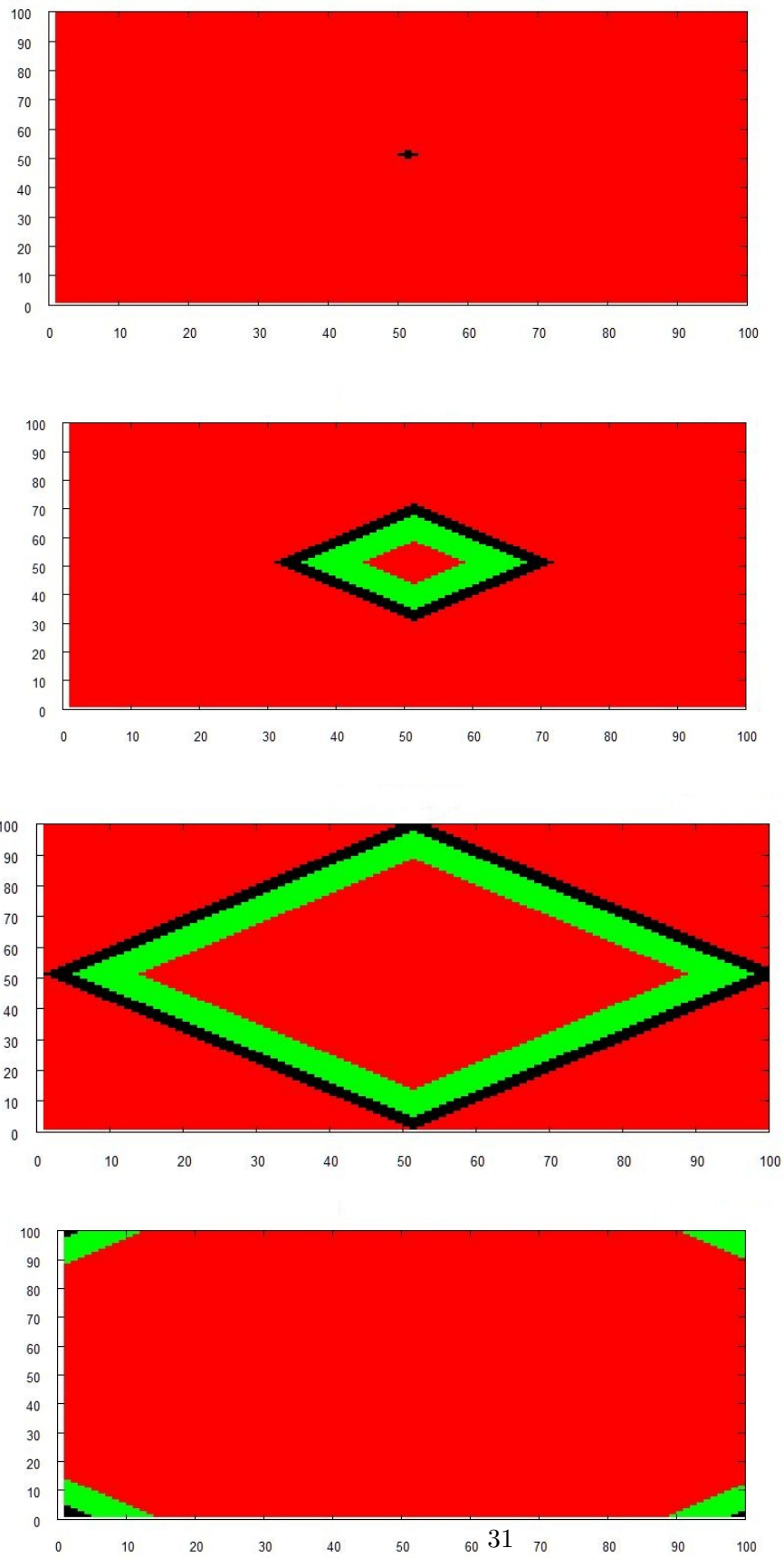


Figure 2.1: Snapshots of the infection spread pattern at different times;  $t= 1, 20, 50, 100$ . [color scheme: Green-refractory;Red-Susceptible;black-infected]

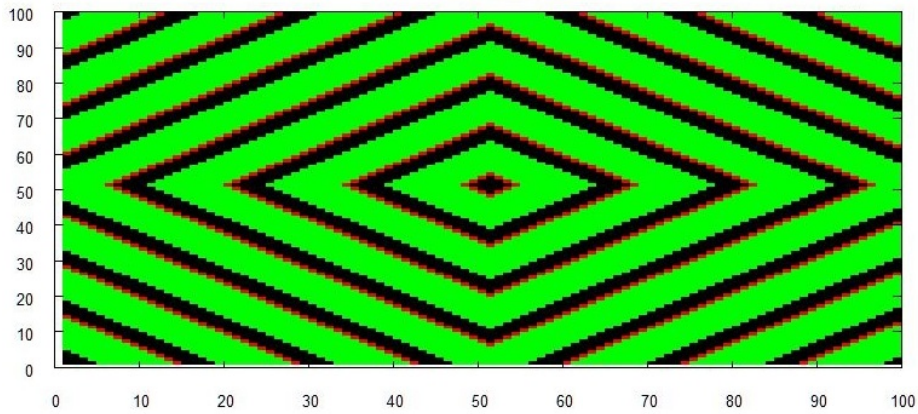


Figure 2.2: Snapshot of the infection spread pattern at time=100[color scheme: Green-refractory;Red-Susceptible;black-infected]

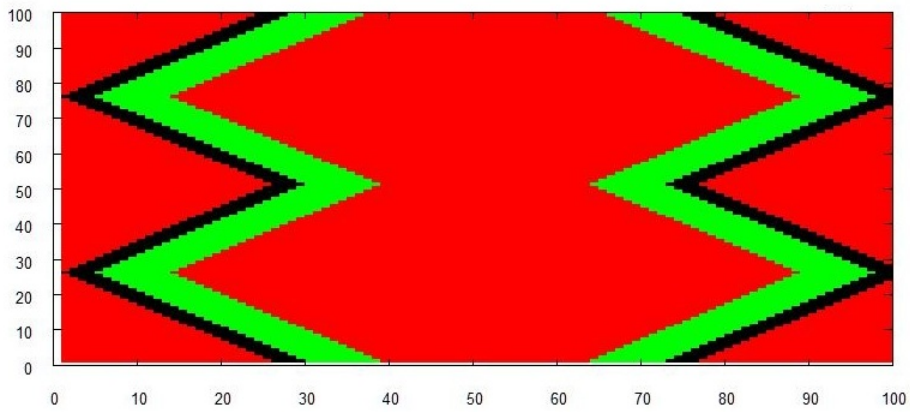


Figure 2.3: Snapshot of the infection spread pattern at time=50[color scheme: Green-refractory;Red-Susceptible;black-infected]

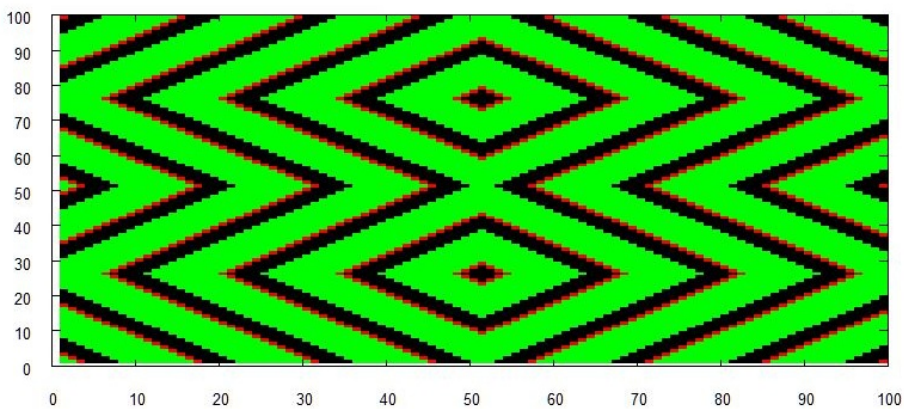


Figure 2.4: Snapshot of the infection spread pattern at time=100[color scheme: Green-refractory;Red-Susceptible;black-infected]

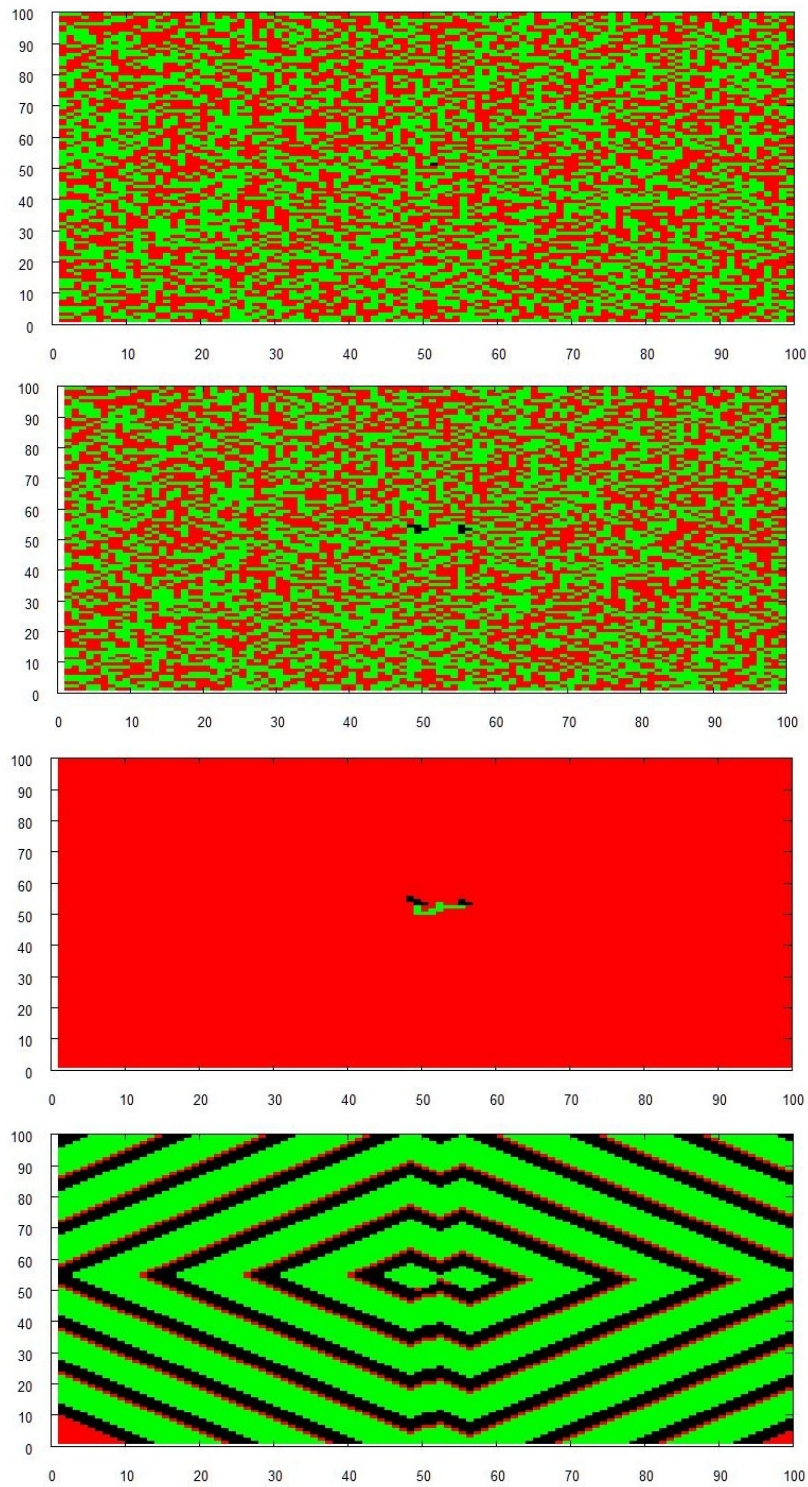


Figure 2.5: Snapshots of the infection spread pattern at time=0,5,8,9,20,100 (order-left to right & top to bottom)[color scheme: Green-refractory;Red-Susceptible;black-infected]



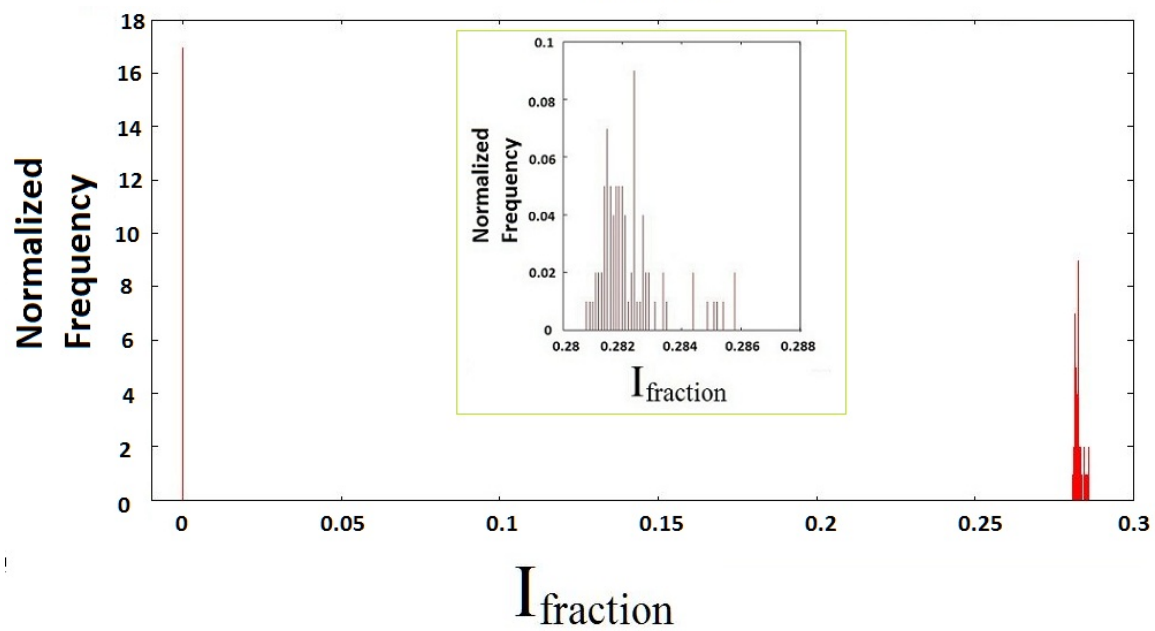
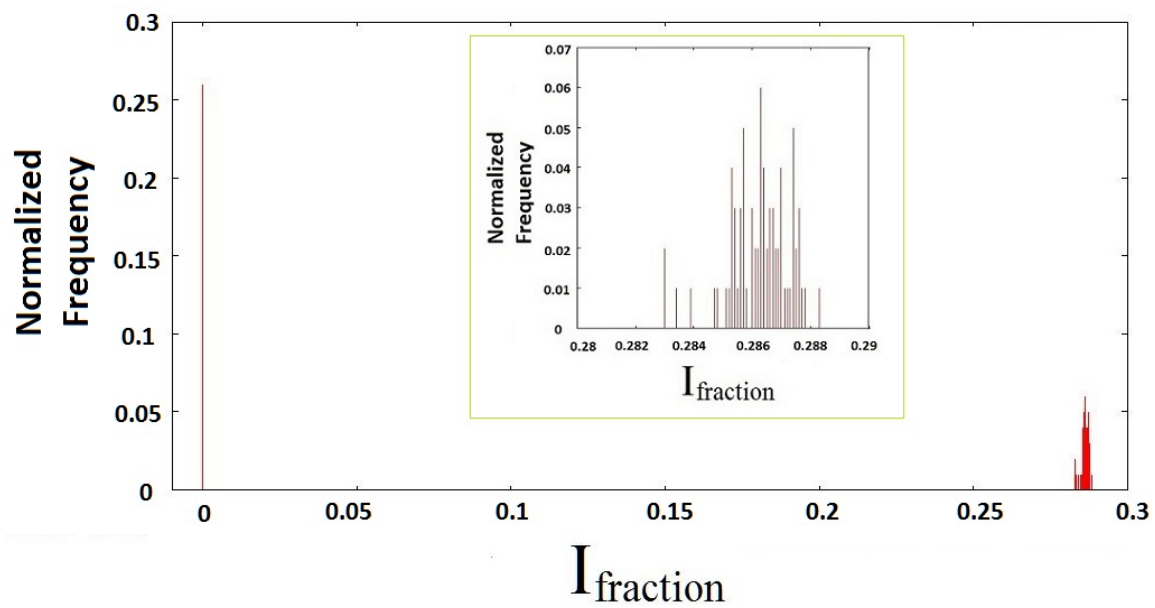


Figure 2.6: Histogram for  $I_t$  after  $t=200$   $[S_0:R_0 - 0.5:0.5]$ (top) &  $[S_0:R_0 - 0.75:0.25]$  ; initially infection put at the center with  $\tau_I = 4$ ;  $\tau_0 = 13$

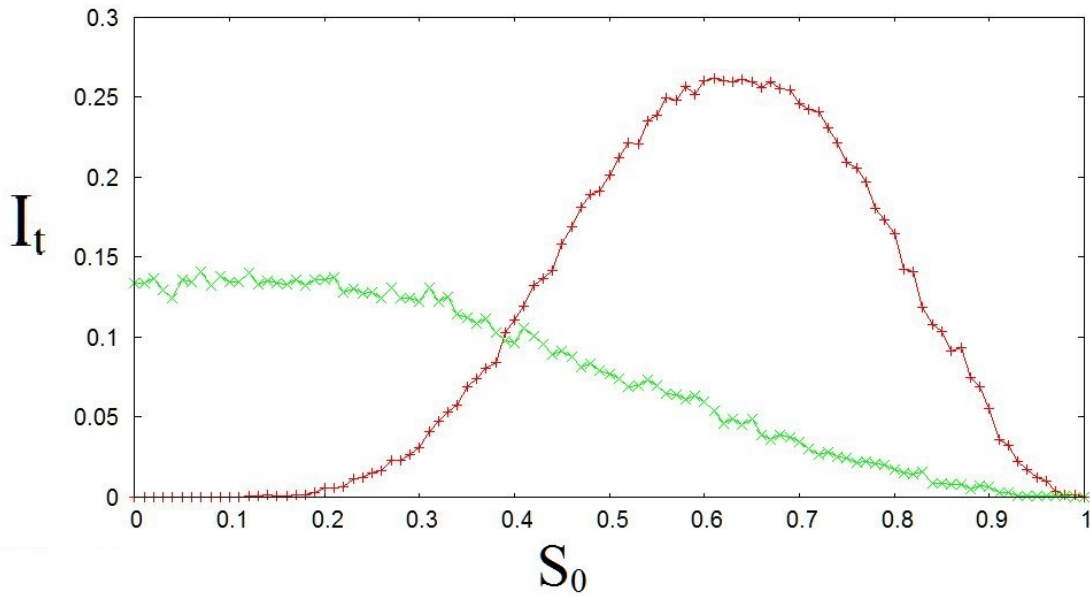


Figure 2.7: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  (Red curve- R population with same phase; Green curve- R population with randomly different phase)[initially infection put at the center]  $N=40 \times 40$ ;  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

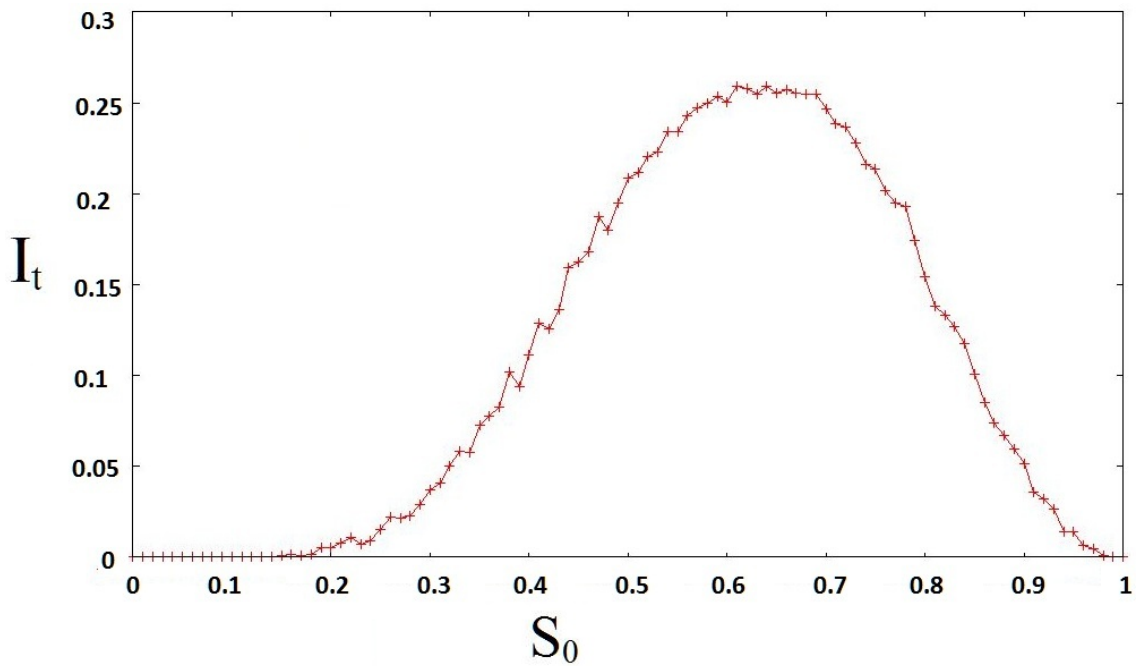


Figure 2.8: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$ . Refractory population having same phase in R [ $\tau_R = \tau_I + 1 = 5$ ].  $\tau_I = 4$ ,  $\tau_R = 9$ .  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations

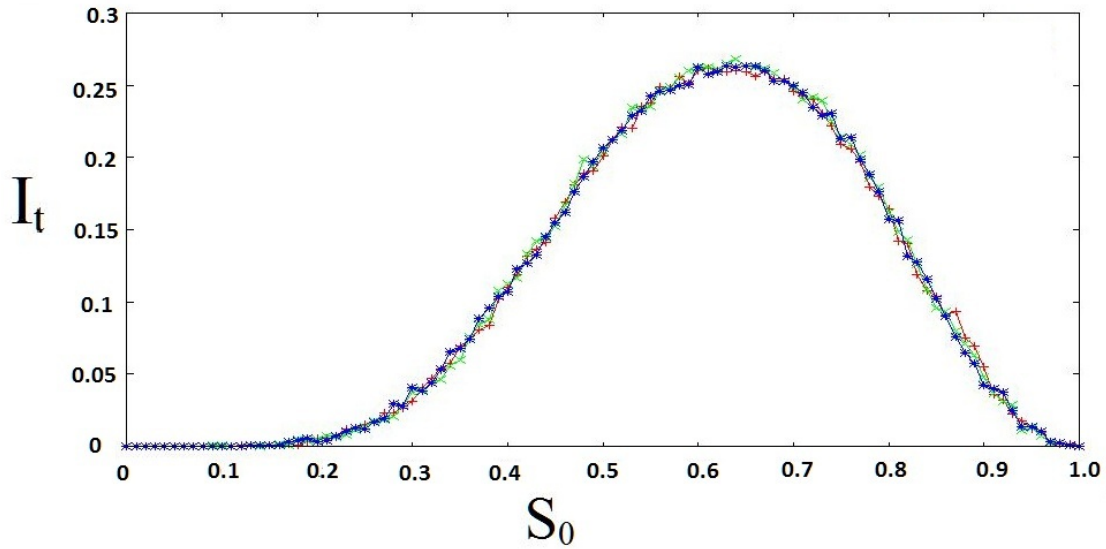


Figure 2.9: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  for population having same phase in R.  $N = 40 \times 40$  (Red curve);  $100 \times 100$  (Green curve);  $70 \times 70$  (Blue curve) [initially infection put at the center]  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

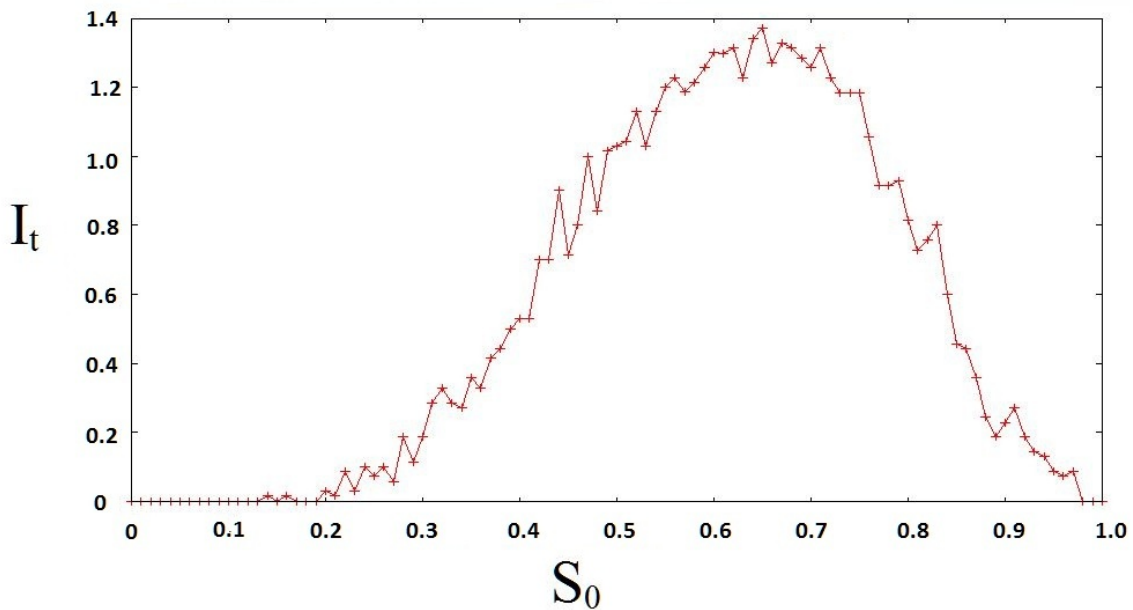


Figure 2.10: Variation of  $I_t$  (averaged over  $t = [200, 300]$ ) with  $S_0$  for population having same phase in R.  $N = 40 \times 40$  [initially infection put at the center]  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

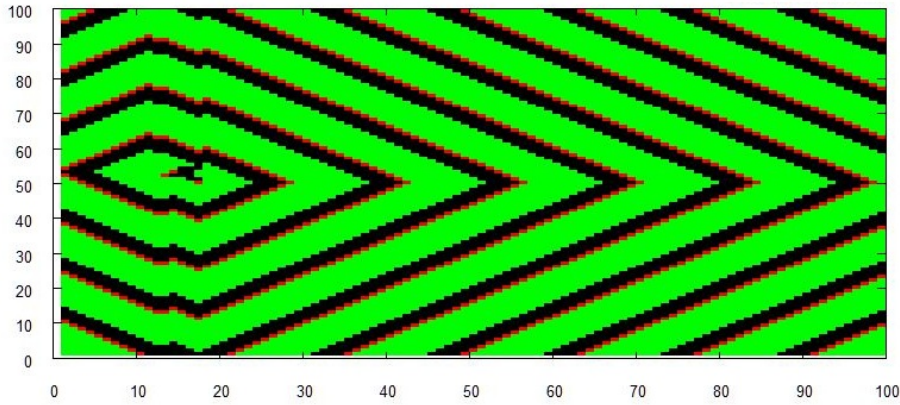


Figure 2.11: Snapshot of the infection spread pattern at  $t=200$  and initially infection at a random site with  $\tau_I = 4$ ;  $\tau_0 = 13$  and  $[S_0:R_{fraction} - 0.5:0.5]$  [color scheme: Green-R; Red-S; black-I]

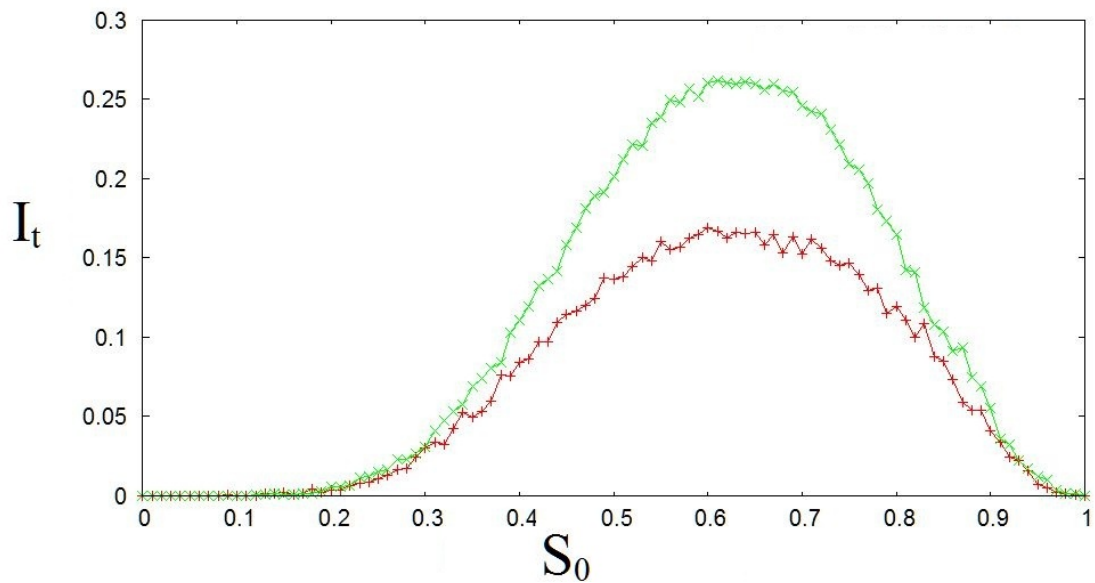


Figure 2.12: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  (Red curve- initial infection at random site; Green curve- initial infection at the center) [with "R" population having fixed same phase.]  $N=40 \times 40$ ;  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

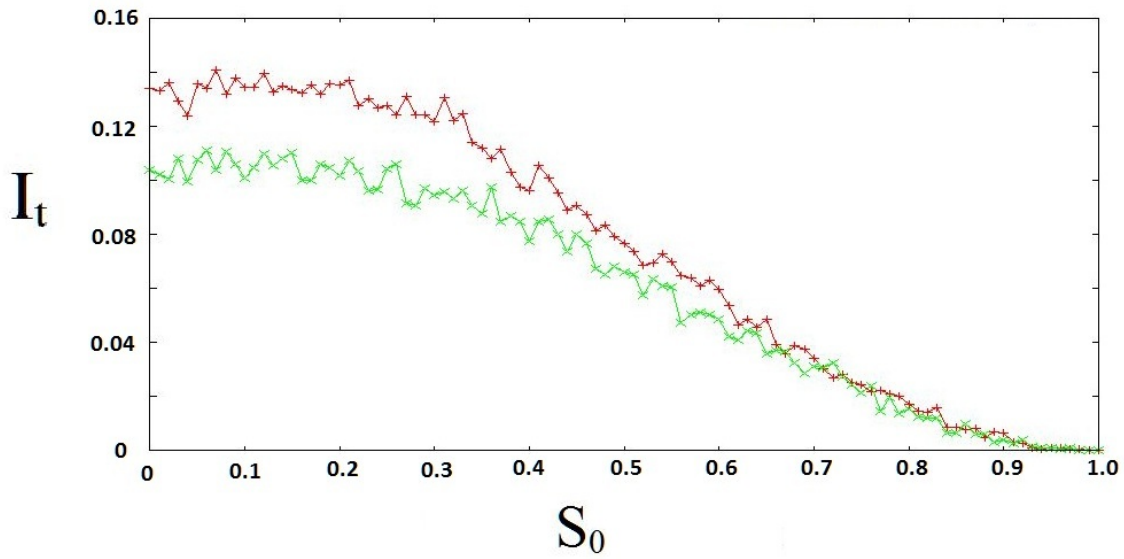


Figure 2.13: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  (Red curve- initial infection at random site; Green curve- initial infection at the center) [with "R" population having randomly different phases.]  $N=40 \times 40$ ;  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

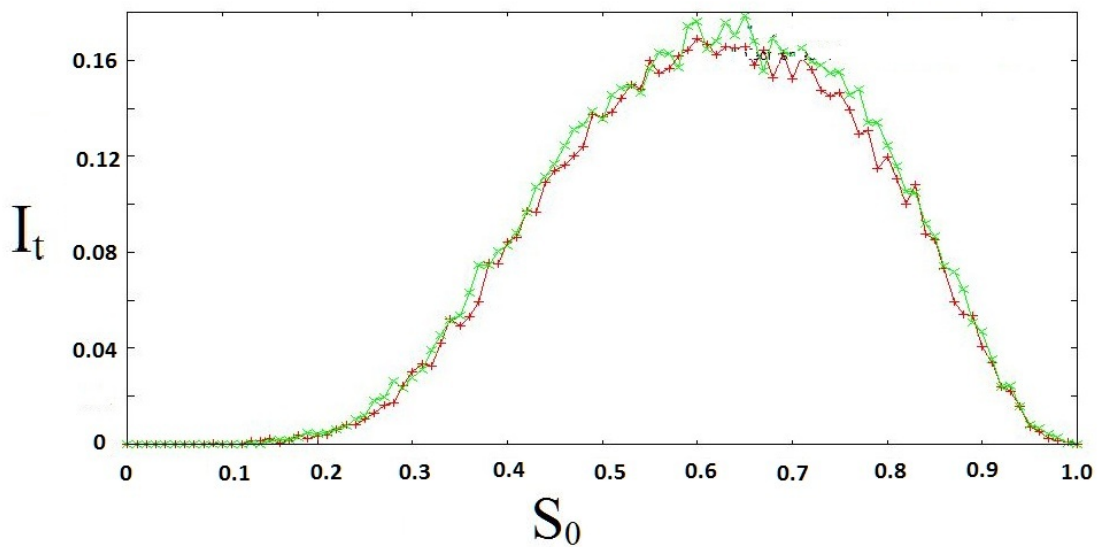


Figure 2.14: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$ .  $N=40 \times 40$  (red curve);  $100 \times 100$  (green curve). [initial infection at random site];  $\tau_I = 4$ ;  $\tau_0 = 13$ , averaged over  $10^3$  realizations.

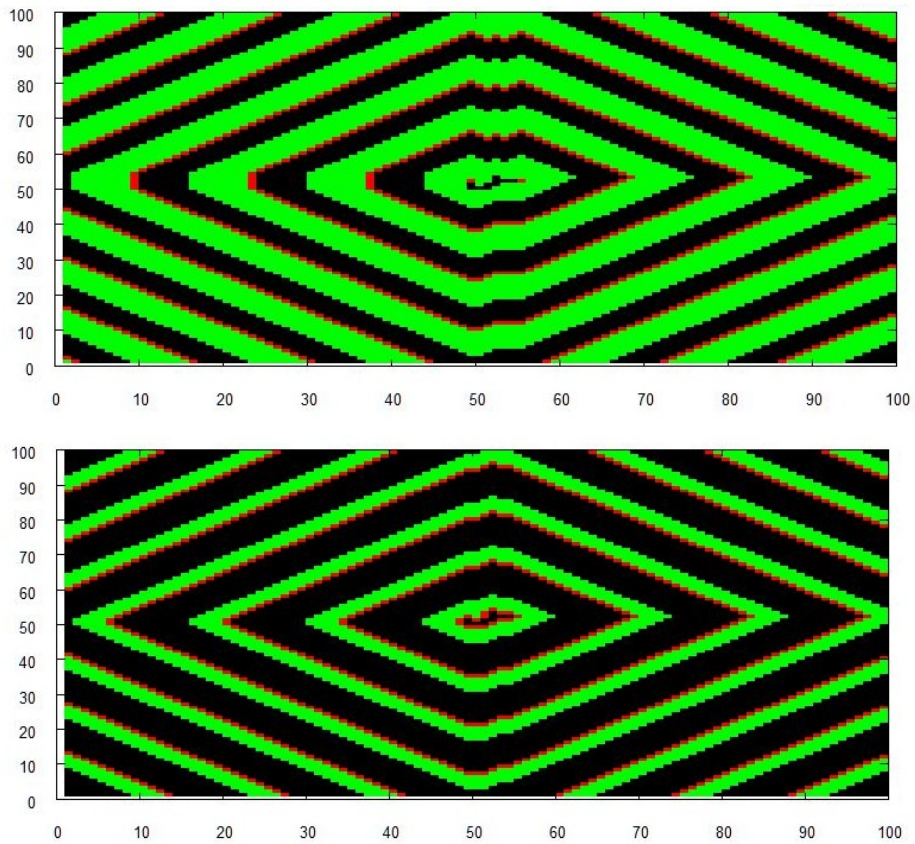


Figure 2.15: Snapshot of the infection spread pattern at  $t=200$  and initially infection put at the center with  $\tau_I = 6$ [left] &  $\tau_I = 9$ [right];  $\tau_0 = 13$  and  $[S_0:R_{fraction} - 0.5:0.5]$ . [color scheme: Green-refractory;Red-Susceptible;black-infected]

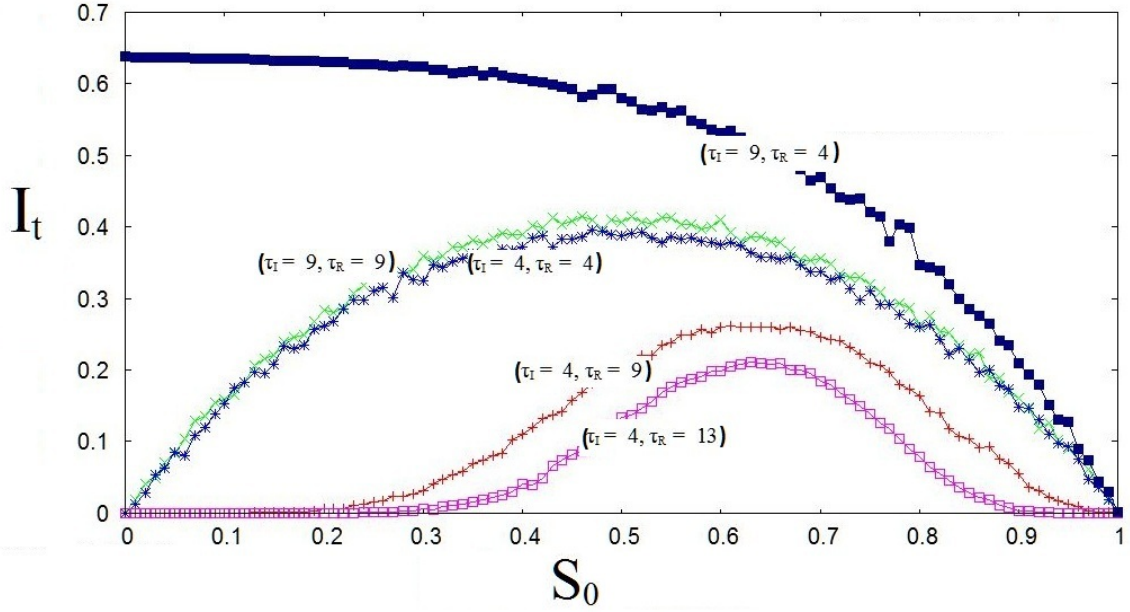


Figure 2.16: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  for population having same phase in R  $\tau_I = 4, \tau_R = 9$ (red curve);  $\tau_I = 4, \tau_R = 13$  (pink curve);  $\tau_I = 4, \tau_R = 4$  (blue curve with crosses);  $\tau_I = 9, \tau_R = 9$  (green curve);  $\tau_I = 9, \tau_R = 4$  (blue curve with boxes).  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations.

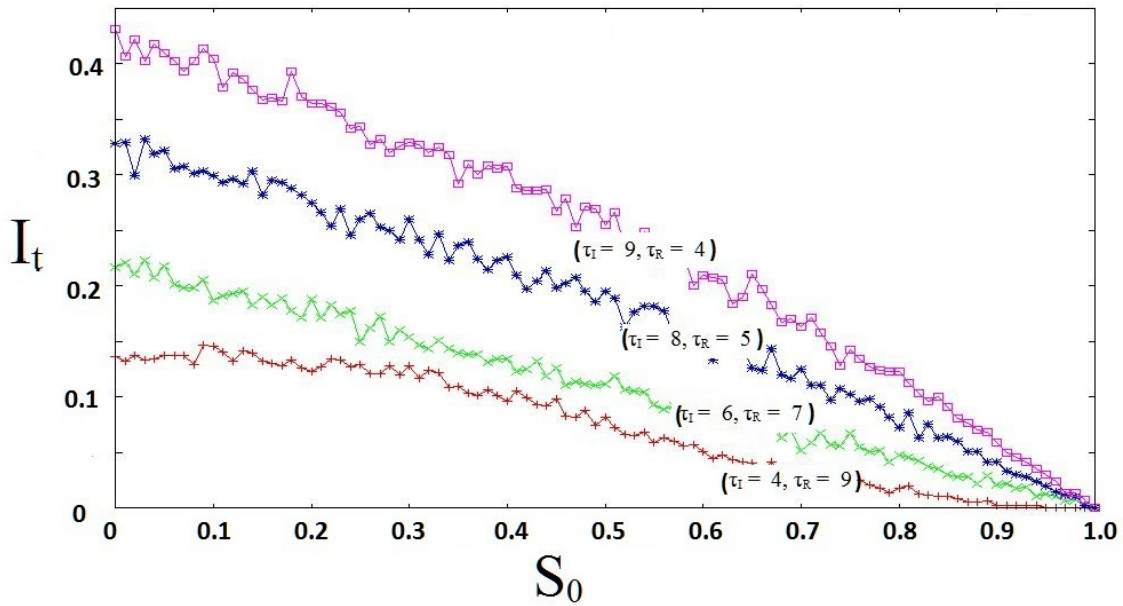


Figure 2.17: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  for population having randomly different phase in R  $\tau_I = 4, \tau_R = 9$ (red curve);  $\tau_I = 6, \tau_R = 7$  (green curve);  $\tau_I = 8, \tau_R = 5$  (blue curve);  $\tau_I = 9, \tau_R = 4$  (pink curve).  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations

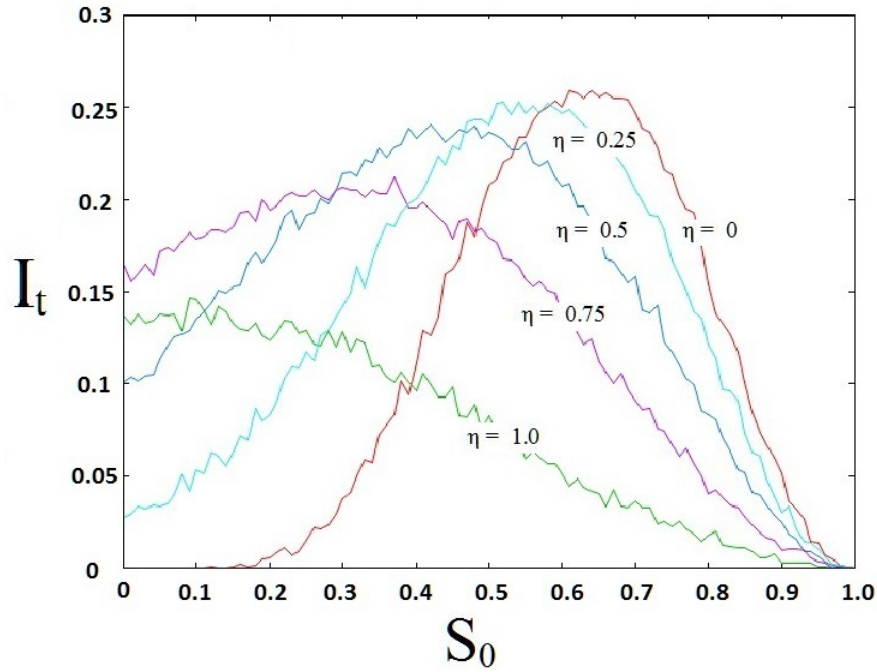


Figure 2.18: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  ( $\eta$ : 0; 0.25; 0.5; 0.75; 1.0).  $\tau_I = 4$ ,  $\tau_0 = 13$ .  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations

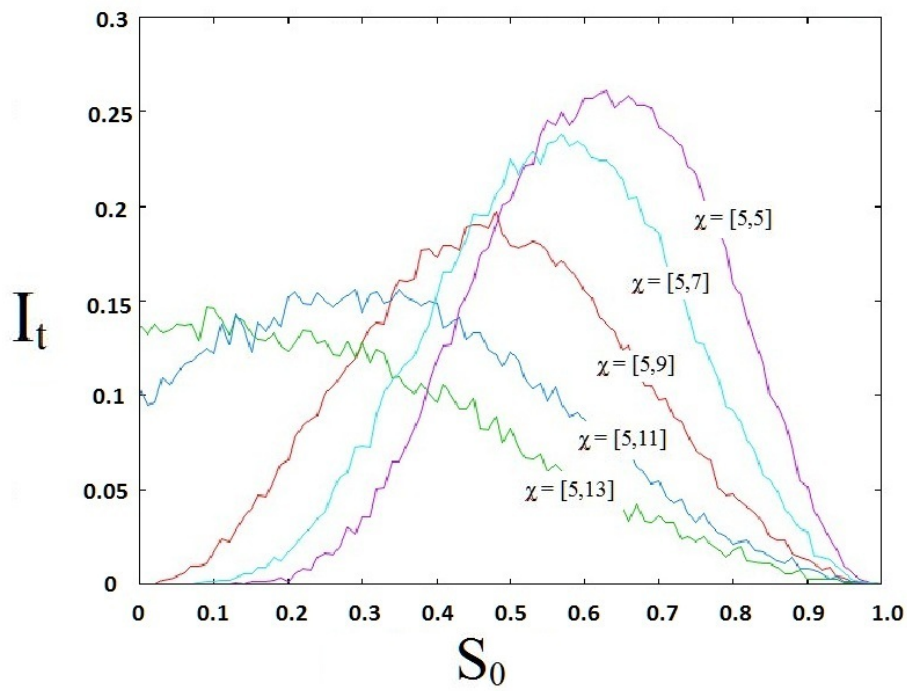


Figure 2.19: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  ( $\chi$ : [5,5]; [5,7]; [5,9]; [5,11]; [5,13]).  $\tau_I = 4$ ,  $\tau_0 = 13$ .  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations



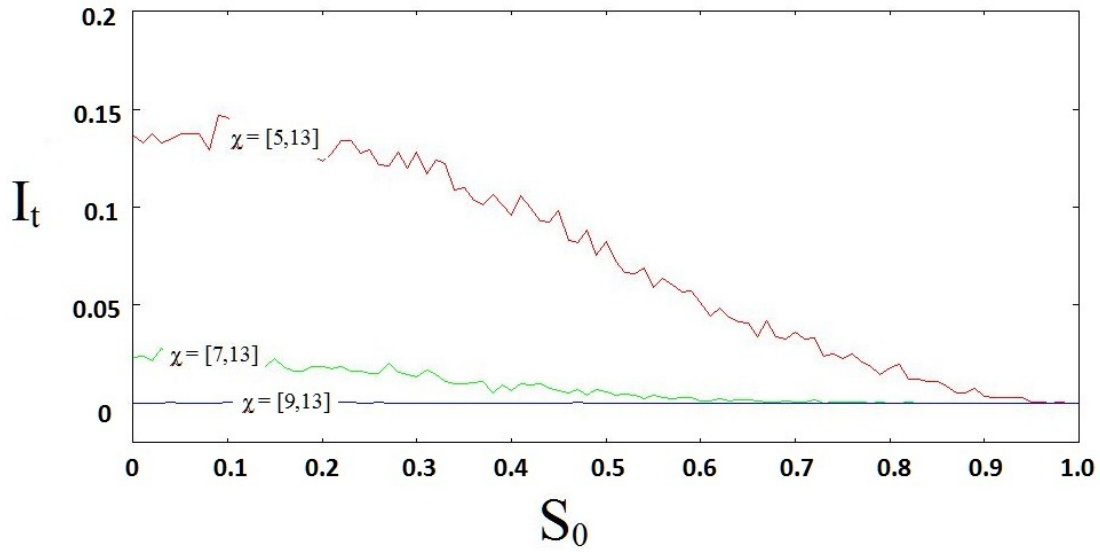


Figure 2.20: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$  ( $\chi$ :  $[5,13]$ ;  $[7,13]$ ;  $[9,13]$ )  $\tau_I = 4$ ,  $\tau_0 = 13$ .  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations

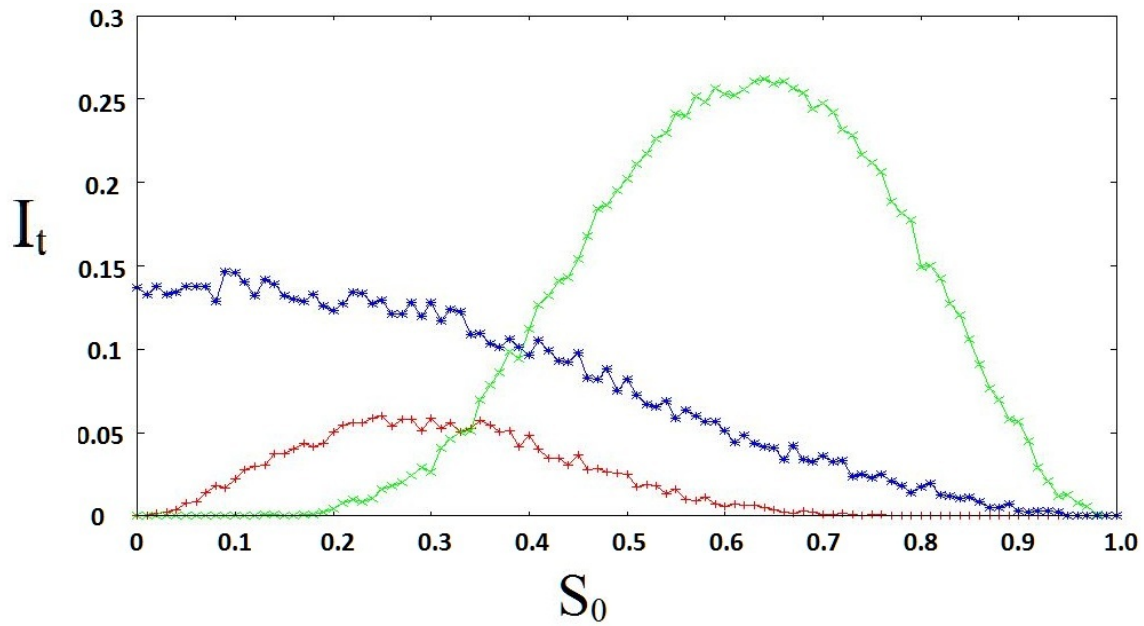


Figure 2.21: Variation of  $I_t$  (after  $t=200$ ) with  $S_0$ . Refractory population having randomly different phase in  $R$  [ $\chi$ :  $[5,13]$ ] (blue curve); same phase initially [ $\tau_R = 9$ ] (red curve); same phase initially [ $\tau_R = 4$ ] (green curve).  $\tau_I = 4$ ,  $\tau_R = 9$ .  $N = 40 \times 40$ . [initial infection at the center]. averaged over  $10^3$  realizations

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